

Description

The AP62400/AP62401 is a 4A, synchronous buck converter with a wide input voltage range of 4.2V to 18V. The device fully integrates a 50mΩ high-side power MOSFET and a 22mΩ low-side power MOSFET to provide high-efficiency step-down DC-DC conversion.

The AP62400/AP62401 device is easily used by minimizing the external component count due to its adoption of Constant On-Time (COT) control to achieve fast transient response, easy loop stabilization, and low output voltage ripple.

The AP62400/AP62401 design is optimized for Electromagnetic Interference (EMI) reduction. The device has a proprietary gate driver scheme to resist switching node ringing without sacrificing MOSFET turn-on and turn-off times, which reduces high-frequency radiated EMI noise caused by MOSFET switching.

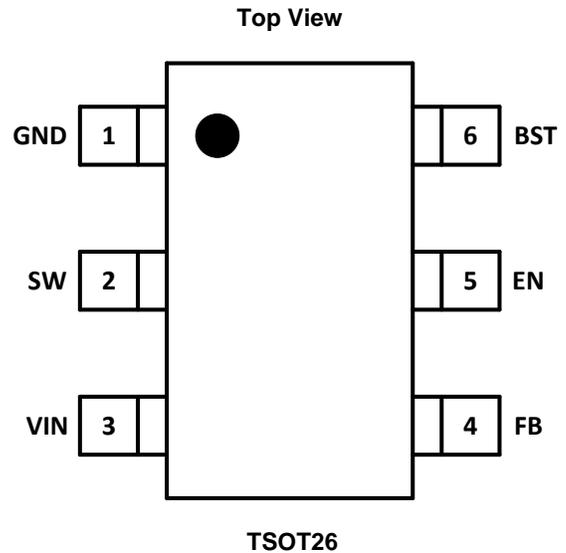
AP62400/AP62401 is available in TSOT26 package.

Features

- VIN: 4.2V to 18V
- Output Voltage (VOUT): 0.8V to 7V
- 4A Continuous Output Current
- 0.8V ± 1% Reference Voltage (T_A = +25°C)
- 190µA Low Quiescent Current (Pulse Frequency Modulation)
- 800kHz Switching Frequency (VIN = 12V, VOUT = 5V)
- Up to 83% Efficiency at 5mA Light Load
- Proprietary Gate Driver Design for Best EMI Reduction
- Protection Circuitry
 - Undervoltage Lockout (UVLO)
 - Cycle-by-Cycle Valley Current Limit
 - Thermal Shutdown
- **Totally Lead-Free & Fully RoHS Compliant (Notes 1 & 2)**
- **Halogen and Antimony Free. "Green" Device (Note 3)**
- **For automotive applications requiring specific change control (i.e. parts qualified to AEC-Q100/101/104/200, PPAP capable, and manufactured in IATF 16949 certified facilities), please [contact us](https://www.diodes.com/contact-us) or your local Diodes representative. <https://www.diodes.com/quality/product-definitions/>**

- Notes:
1. No purposely added lead. Fully EU Directive 2002/95/EC (RoHS), 2011/65/EU (RoHS 2) & 2015/863/EU (RoHS 3) compliant.
 2. See <https://www.diodes.com/quality/lead-free/> for more information about Diodes Incorporated's definitions of Halogen- and Antimony-free, "Green" and Lead-free.
 3. Halogen- and Antimony-free "Green" products are defined as those which contain <900ppm bromine, <900ppm chlorine (<1500ppm total Br + Cl) and <1000ppm antimony compounds.

Pin Assignments



Applications

- 5V and 12V distributed power bus supplies
- Flat screen TV sets and monitors
- White goods and small home appliances
- FPGA, DSP, and ASIC supplies
- Home audio
- Network systems
- Gaming consoles
- Consumer electronics
- General-purpose point of loads

Typical Application Circuit

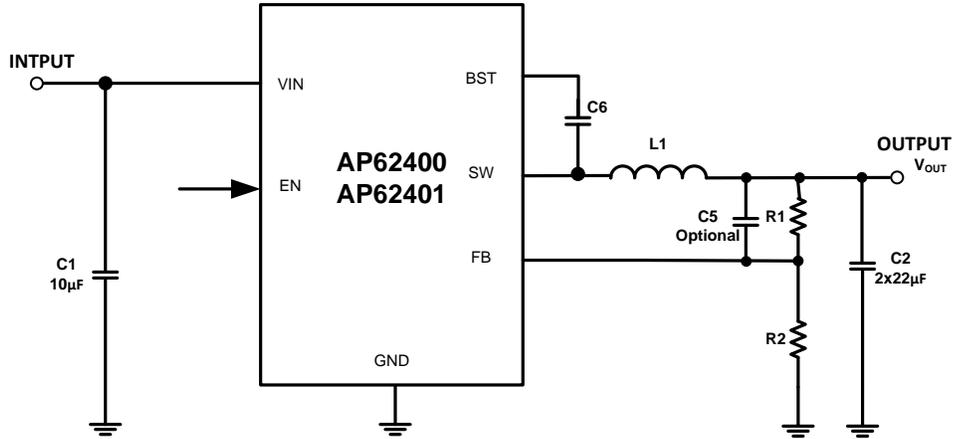


Figure 1. Typical TSOT26 Package Application Circuit

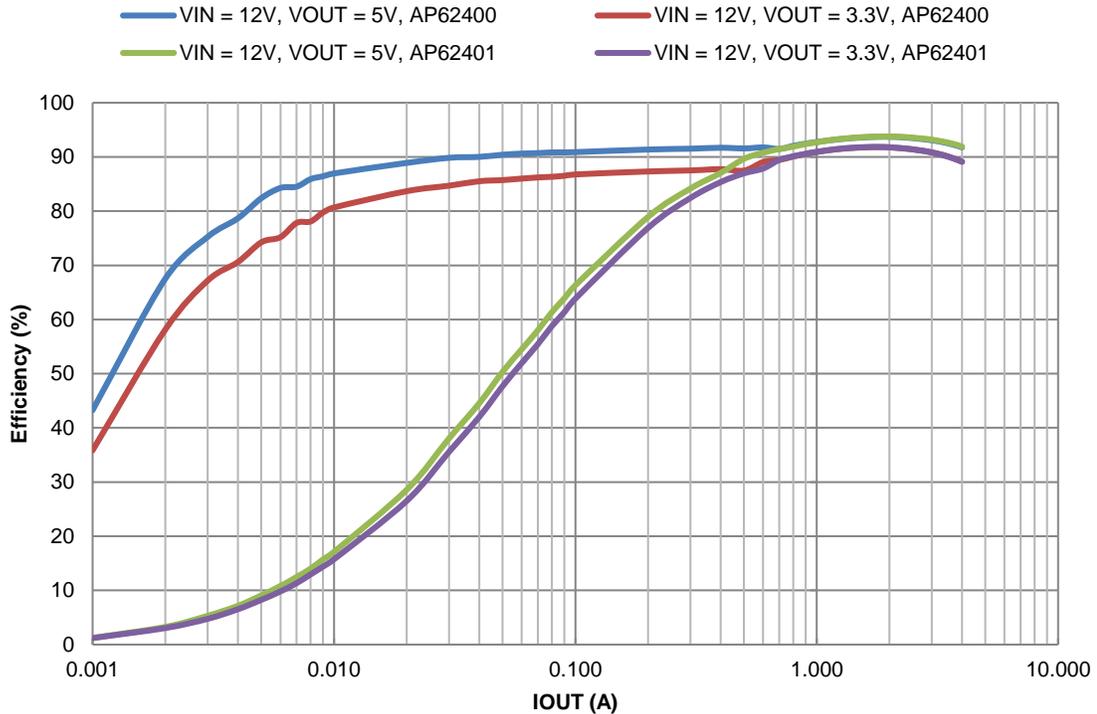


Figure 2. Efficiency vs. Output Current, AP62400 & AP62401

Pin Descriptions

Pin Name	Pin Number	Function
GND	1	Power Ground.
SW	2	Power Switching Output. SW is the switching node that supplies power to the output. Connect the output LC filter from SW to the output load.
VIN	3	Power Input. VIN supplies the power to the IC as well as the step-down converter power MOSFETs. Drive VIN with a 4.2V to 18V power source. Bypass VIN to GND with a suitably large capacitor to eliminate noise due to the switching of the IC. See <i>Input Capacitor</i> section for more details.
FB	4	Feedback Sensing Terminal for the Output Voltage. Connect this pin to the resistive divider of the output. See <i>Setting the Output Voltage</i> section for more details.
EN	5	Enable Input. EN is a digital input that turns the regulator on or off. Drive EN high to turn on the regulator and low to turn it off. Leave floating for automatic startup. The EN has a precision threshold of 1.2V for programming the UVLO. See <i>Enable</i> section for more details.
BST	6	High-Side Gate Drive Boost Input. BST supplies the drive for the high-side n-Channel MOSFET. A 100nF capacitor is recommended from BST to SW to power the high-side driver.

Functional Block Diagram

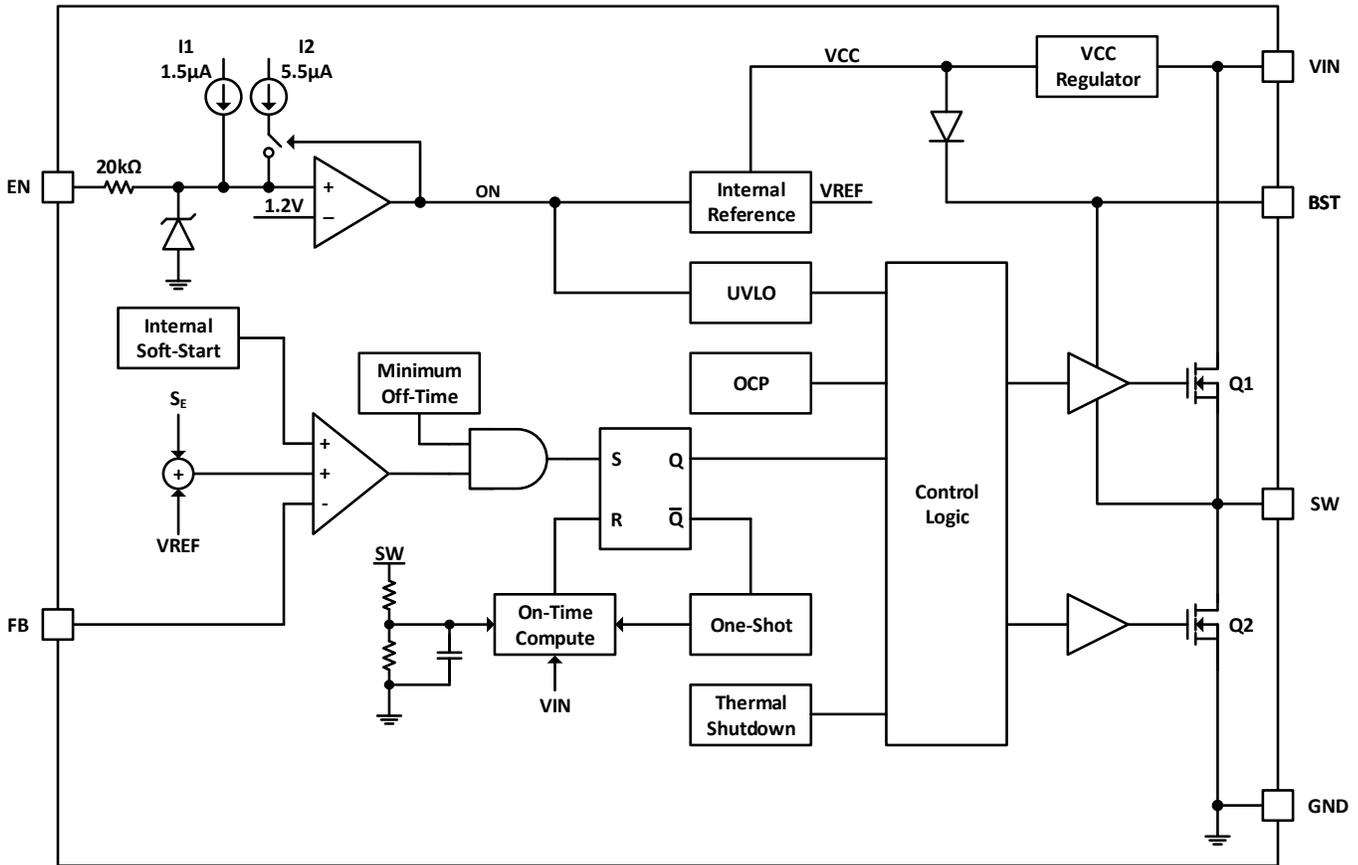


Figure 3. Functional Block Diagram, 6-Pin AP62400/AP62401

Absolute Maximum Ratings (Note 4) (@ T_A = +25°C, unless otherwise specified.)

Symbol	Parameter	Rating	Unit
V _{IN}	Supply Pin Voltage	-0.3 to +20.0 (DC)	V
		-0.3 to +22.0 (400ms)	
V _{SW}	Switch Pin Voltage	-1.0 to V _{IN} + 0.3 (DC)	V
		-2.5 to V _{IN} + 2.0 (20ns)	
V _{FB}	Feedback Pin Voltage	-0.3 to +6.0	V
V _{EN}	Enable/UVLO Pin Voltage	-0.3 to +7.0	V
V _{BST}	Bootstrap Pin Voltage	V _{SW} - 0.3 to V _{SW} + 6.0	V
T _{ST}	Storage Temperature	-65 to +150	°C
T _J	Junction Temperature	+160	°C
T _L	Lead Temperature	+260	°C
ESD Susceptibility (Note 5)			
HBM	Human Body Model	±2000	V
CDM	Charged Device Model	±500	V

- Notes:
- Stresses greater than those listed under *Absolute Maximum Ratings* can cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to *Absolute Maximum Ratings* for extended periods can affect device reliability.
 - Semiconductor devices are ESD sensitive and can be damaged by exposure to ESD events. Suitable ESD precautions should be taken when handling and transporting these devices.

Thermal Resistance (Note 6)

Symbol	Parameter	Rating		Unit
θ _{JA}	Junction to Ambient	TSOT26	70	°C/W
θ _{JC}	Junction to Case	TSOT26	12	°C/W

- Note: 6. Test condition for TSOT26: Device mounted on FR-4 substrate, two-layer PCB, 2oz copper, with minimum recommended pad layout.

Recommended Operating Conditions (Note 7) (@ T_A = +25°C, unless otherwise specified.)

Symbol	Parameter	Min	Max	Unit
V _{IN}	Supply Voltage	4.2	18.0	V
V _{OUT}	Output Voltage	0.8	7.0	V
T _A	Operating Ambient Temperature	-40	+85	°C
T _J	Operating Junction Temperature	-40	+125	°C

- Note: 7. The device function is not guaranteed outside of the recommended operating conditions.

Electrical Characteristics (@ $T_J = +25^\circ\text{C}$, $V_{IN} = 12\text{V}$, unless otherwise specified. Min/Max limits apply across the recommended operating junction temperature range, -40°C to $+125^\circ\text{C}$, and input voltage range, 4.2V to 18V, unless otherwise specified.)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I _{SHDN}	Shutdown Supply Current	$V_{EN} = 0\text{V}$	—	1.5	—	μA
I _Q	Quiescent Supply Current	AP62400: $V_{FB} = 0.85\text{V}$	—	190	—	μA
		AP62401: $V_{FB} = 0.85\text{V}$	—	440	—	μA
POR	VIN Power-on Reset Rising Threshold	—	—	3.90	4.15	V
UVLO	VIN Undervoltage Lockout Falling Threshold	—	—	3.6	—	V
R _{DS(ON)1}	High-Side Power MOSFET On-Resistance (Note 8)	—	—	50	—	m Ω
R _{DS(ON)2}	Low-Side Power MOSFET On-Resistance (Note 8)	—	—	22	—	m Ω
I _{VALLEY_LIMIT}	LS Valley Current Limit (Note 8)	From Source to Drain	4.0	5.25	6.5	A
f _{SW}	Oscillator Frequency	$V_{OUT} = 5\text{V}$, CCM	—	800	—	kHz
t _{ON_MIN}	Minimum On-Time	—	—	60	—	ns
t _{OFF_MIN}	Minimum Off-Time	—	—	150	—	ns
V _{FB}	Feedback Voltage	AP62400/AP62401: $T_A = +25^\circ\text{C}$, CCM	0.792	0.800	0.808	V
		AP62400/AP62401: CCM	0.784	0.800	0.816	V
V _{EN_H}	EN Logic High Threshold	—	—	1.20	1.25	V
V _{EN_L}	EN Logic Low Threshold	—	1.04	1.10	—	V
I _{EN}	EN Input Current	$V_{EN} = 1.5\text{V}$	—	7.0	—	μA
		$V_{EN} = 1\text{V}$	1.0	1.5	2.0	μA
t _{SS}	Soft-Start Time	—	—	1	—	ms
T _{SD}	Thermal Shutdown (Note 8)	—	—	+160	—	$^\circ\text{C}$
T _{Hys}	Thermal Shutdown Hysteresis (Note 8)	—	—	+20	—	$^\circ\text{C}$

Note: 8. Compliance to the datasheet limits is assured by one or more methods: production test, characterization, and/or design.

Typical Performance Characteristics (AP62400/AP62401 @ $T_A = +25^\circ\text{C}$, $V_{IN} = 12\text{V}$, $V_{OUT} = 5\text{V}$, BOM = Table 1, unless otherwise specified.)

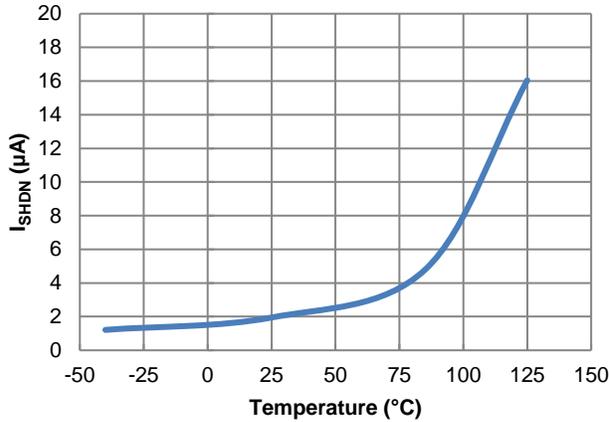


Figure 4. ISHDN vs. Temperature

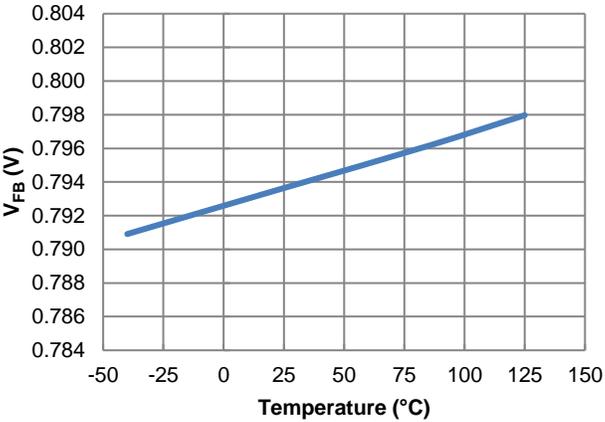


Figure 5. Feedback Voltage vs. Temperature

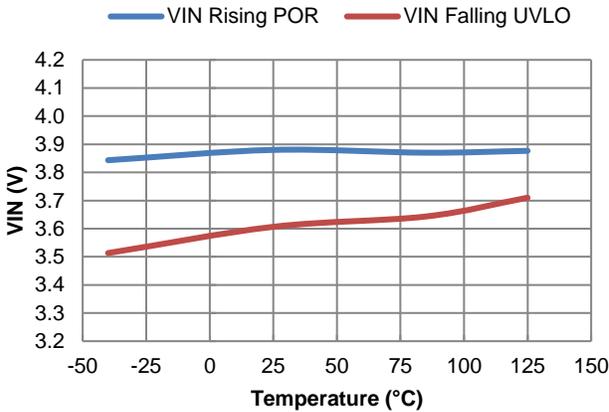


Figure 6. VIN Power-On Reset & UVLO vs. Temperature

Typical Performance Characteristics (AP62400/AP62401 @ $T_A = +25^\circ\text{C}$, $V_{IN} = 12\text{V}$, $V_{OUT} = 5\text{V}$, BOM = Table 1, unless otherwise specified.) (continued)

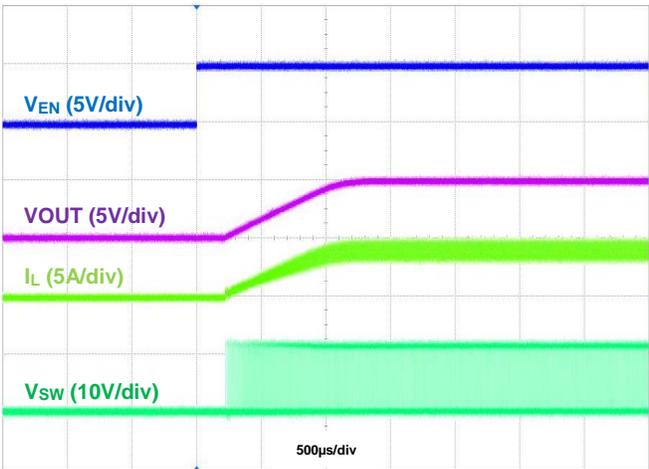


Figure 7. Startup Using EN, IOU = 4A

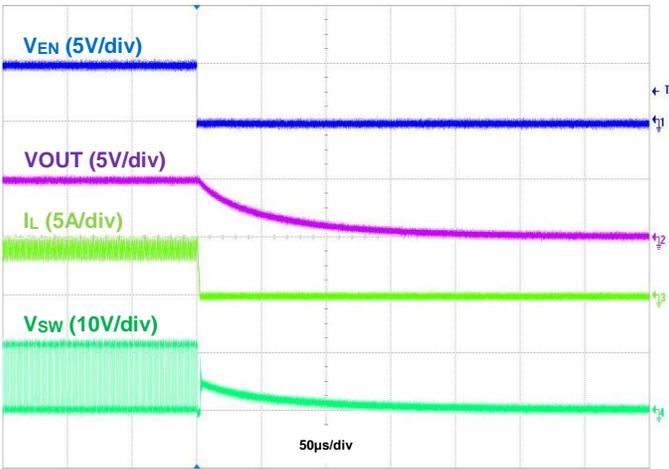


Figure 8. Shutdown Using EN, IOU = 4A

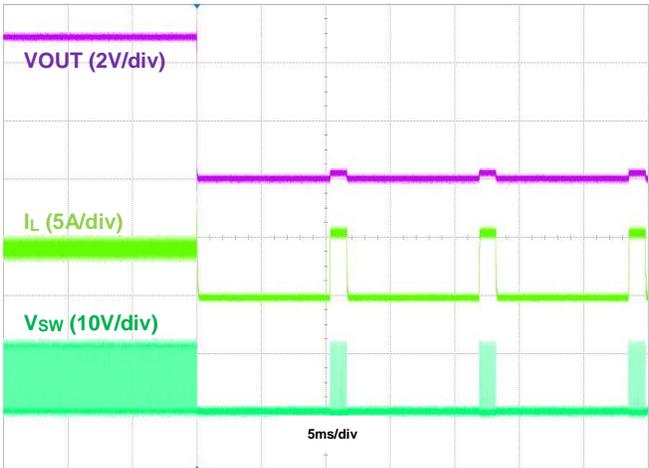


Figure 9. Output Short Protection, IOU = 4A

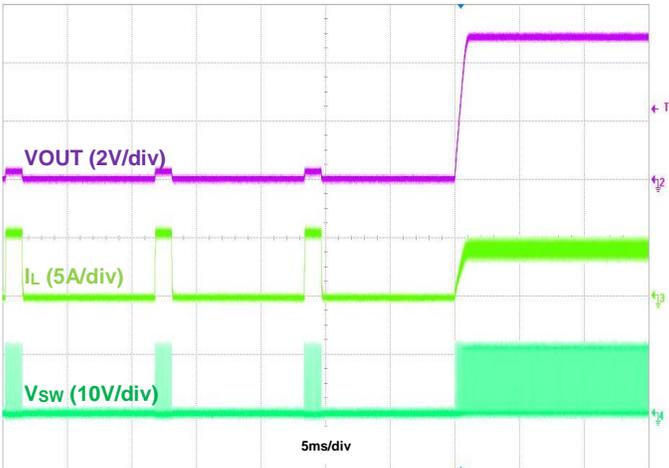


Figure 10. Output Short Recovery, IOU = 4A

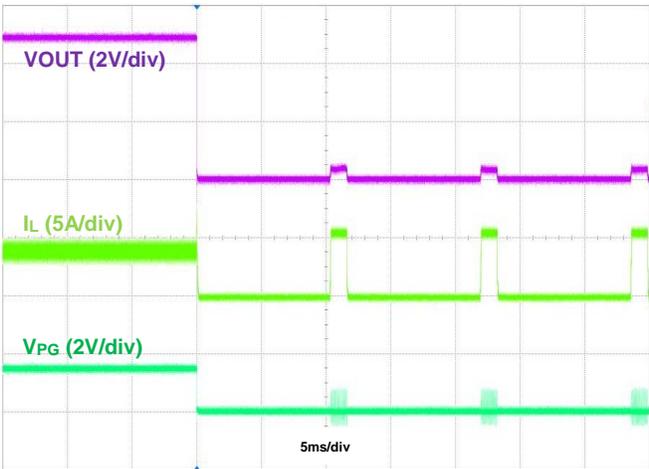


Figure 11. Output Short Protection with PG, IOU = 4A

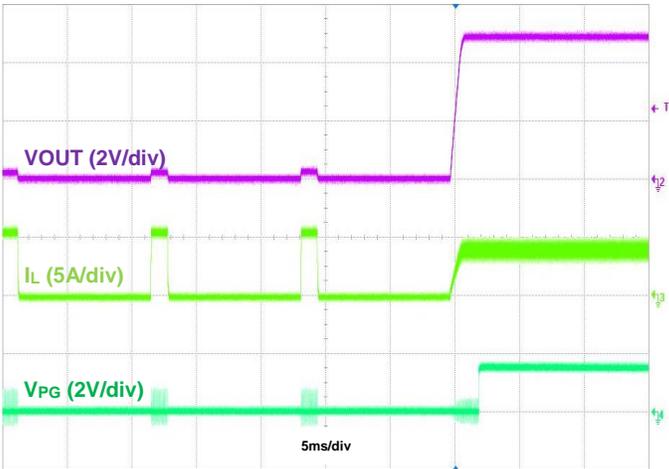


Figure 12. Output Short Recovery with PG, IOU = 4A

Typical Performance Characteristics (AP62400 @ $T_A = +25^\circ\text{C}$, $V_{IN} = 12\text{V}$, $V_{OUT} = 5\text{V}$, BOM = Table 1, unless otherwise specified.)

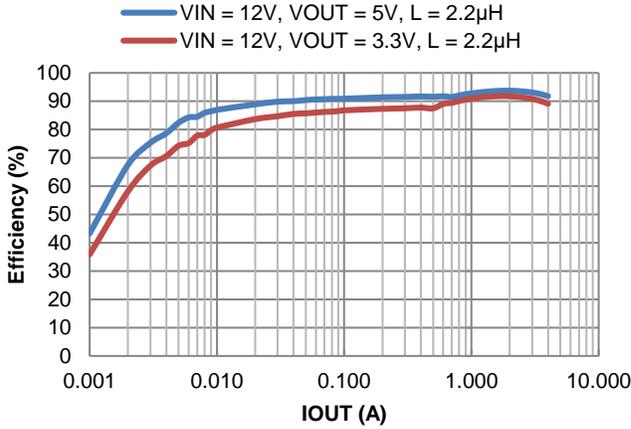


Figure 13. Efficiency vs. Output Current

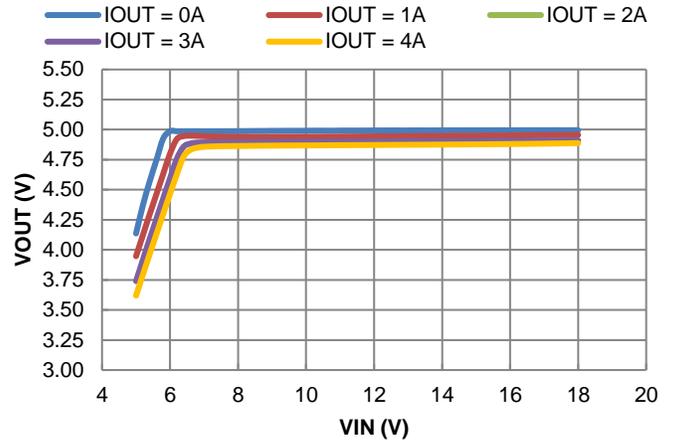


Figure 14. Line Regulation

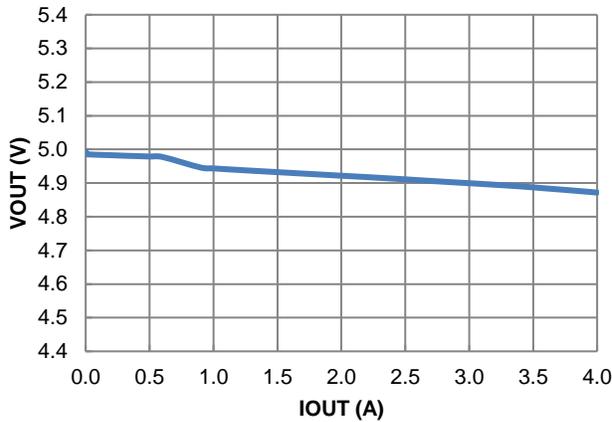


Figure 15. Load Regulation

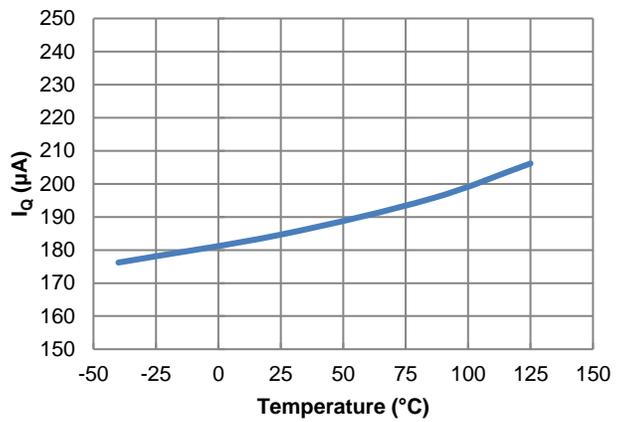


Figure 16. I_Q vs. Temperature

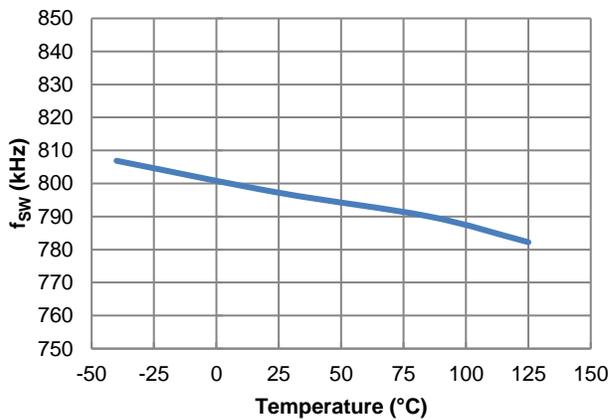


Figure 17. f_{sw} vs. Temperature, $I_{OUT} = 1\text{A}$

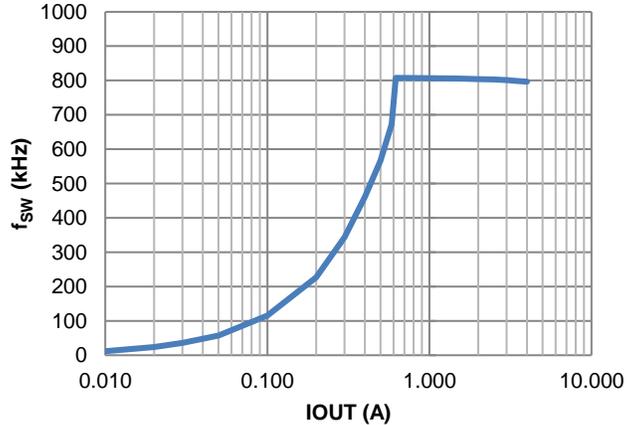


Figure 18. f_{sw} vs. Load

Typical Performance Characteristics (AP62400 @ $T_A = +25^\circ\text{C}$, $V_{IN} = 12\text{V}$, $V_{OUT} = 5\text{V}$, BOM = Table 1, unless otherwise specified.) (continued)

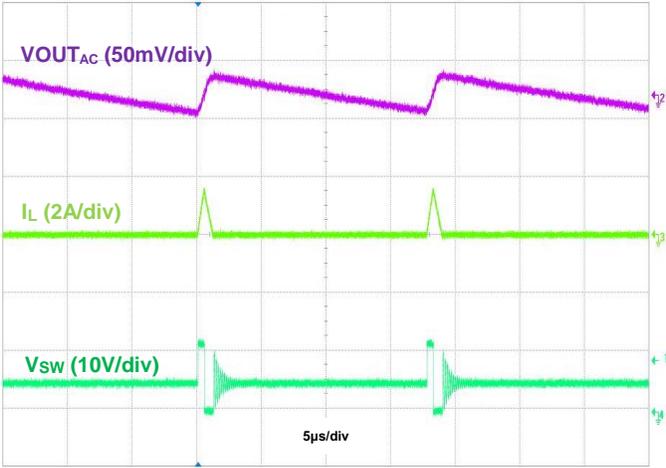


Figure 19. Output Voltage Ripple, $V_{OUT} = 5\text{V}$, $I_{OUT} = 50\text{mA}$

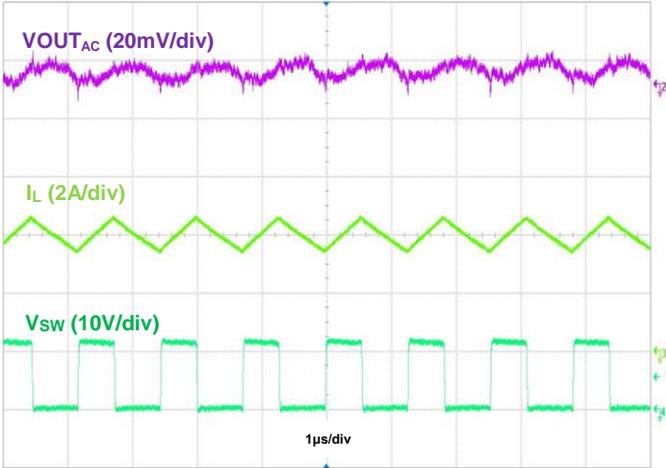


Figure 20. Output Voltage Ripple, $V_{OUT} = 5\text{V}$, $I_{OUT} = 4\text{A}$

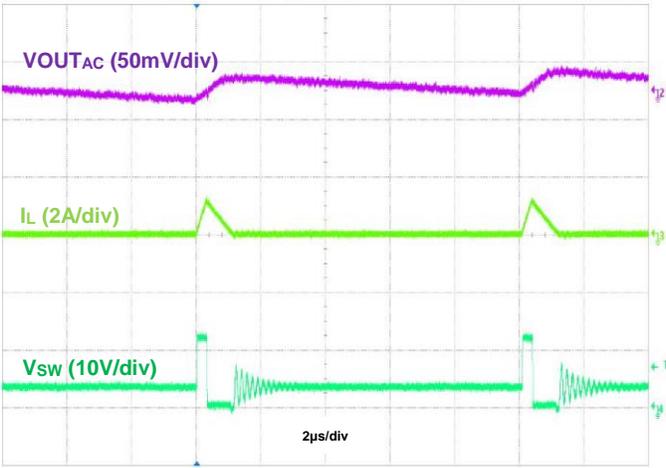


Figure 21. Output Voltage Ripple, $V_{OUT} = 3.3\text{V}$, $I_{OUT} = 50\text{mA}$

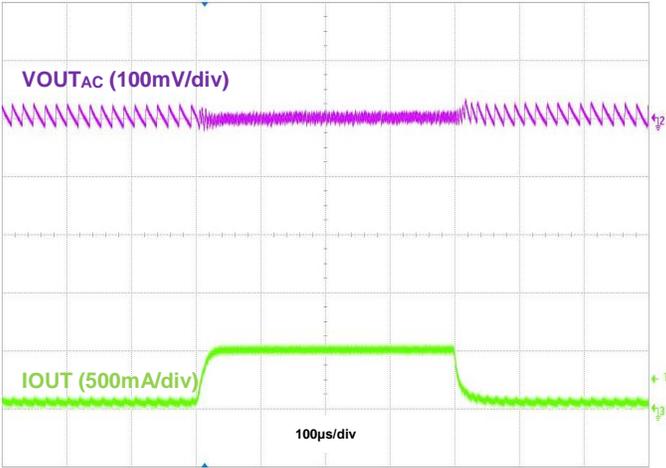


Figure 22. Load Transient, $I_{OUT} = 50\text{mA}$ to 500mA to 50mA

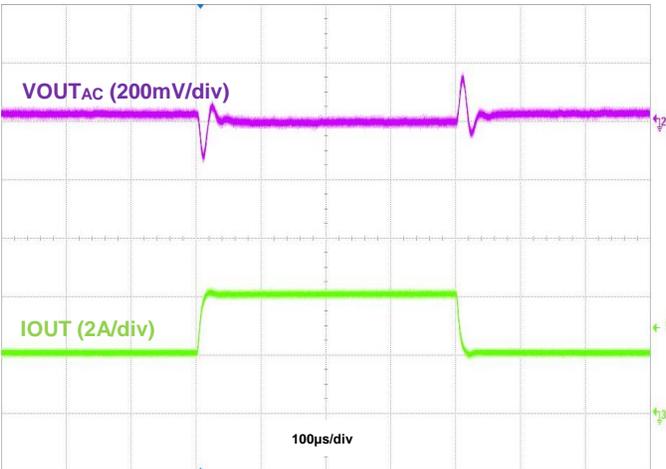


Figure 23. Load Transient, $I_{OUT} = 2\text{A}$ to 4A to 2A

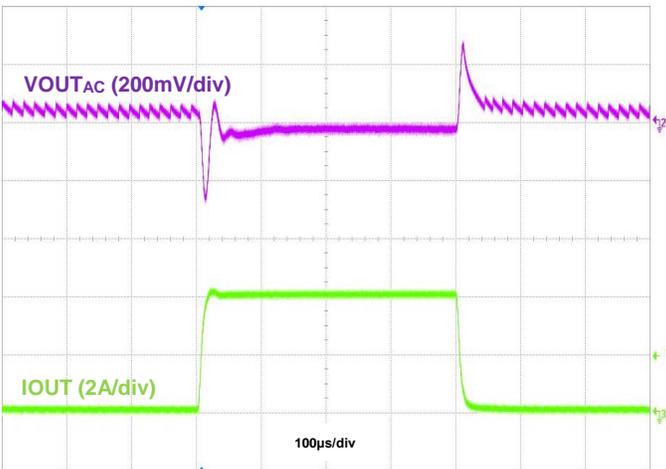


Figure 24. Load Transient, $I_{OUT} = 50\text{mA}$ to 4A to 50mA

Typical Performance Characteristics (AP62401 @ $T_A = +25^\circ\text{C}$, $V_{IN} = 12\text{V}$, $V_{OUT} = 5\text{V}$, BOM = Table 1, unless otherwise specified.)

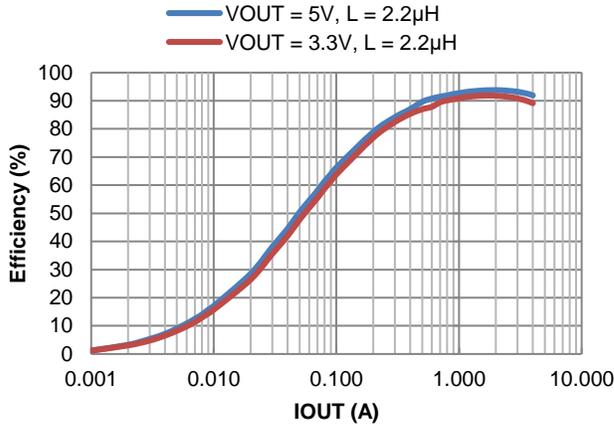


Figure 25. Efficiency vs. Output Current

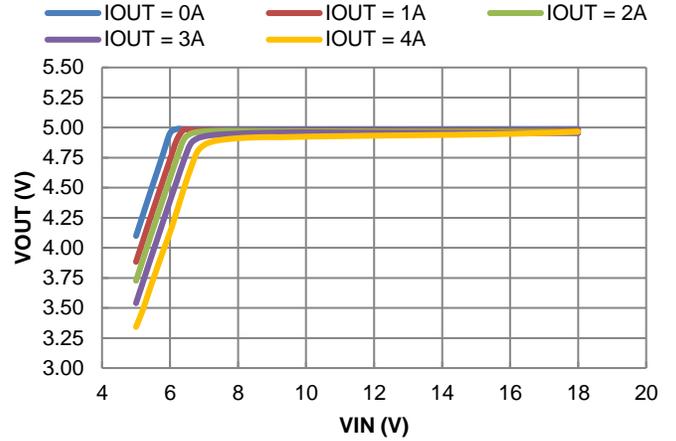


Figure 26. Line Regulation

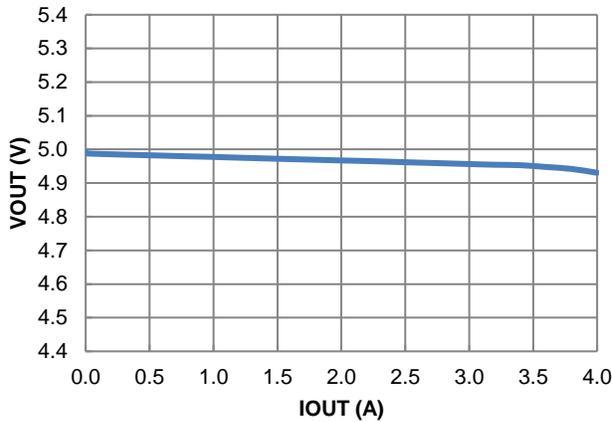


Figure 27. Load Regulation

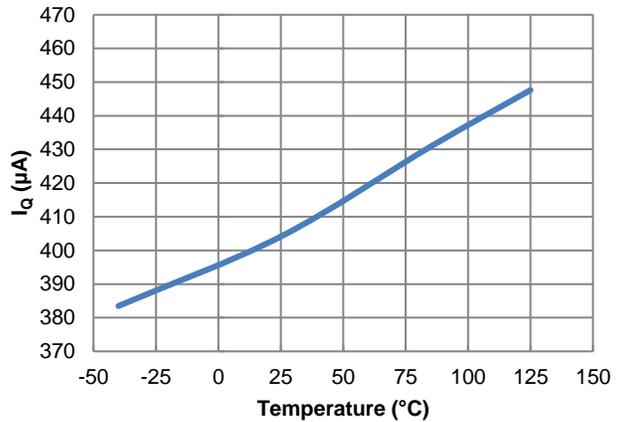


Figure 28. I_Q vs. Temperature

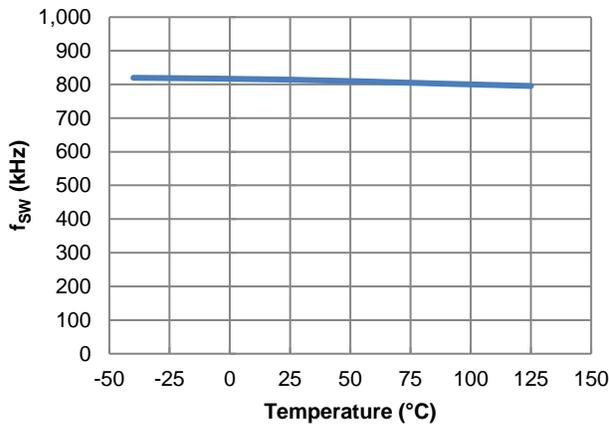


Figure 29. f_{sw} vs. Temperature, $I_{OUT} = 0\text{A}$

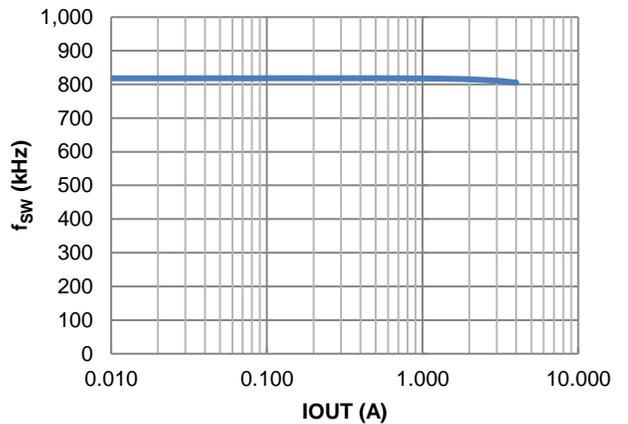


Figure 30. f_{sw} vs. Load

Typical Performance Characteristics (AP62401 @ $T_A = +25^\circ\text{C}$, $V_{IN} = 12\text{V}$, $V_{OUT} = 5\text{V}$, BOM = Table 1, unless otherwise specified.) (continued)

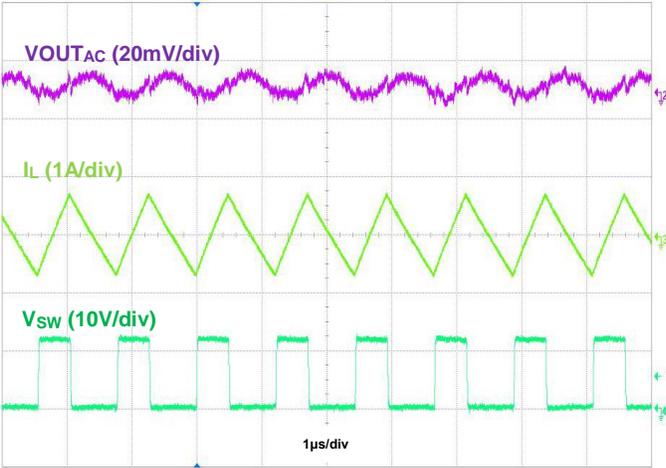


Figure 31. Output Voltage Ripple, $V_{OUT} = 5\text{V}$, $I_{OUT} = 50\text{mA}$

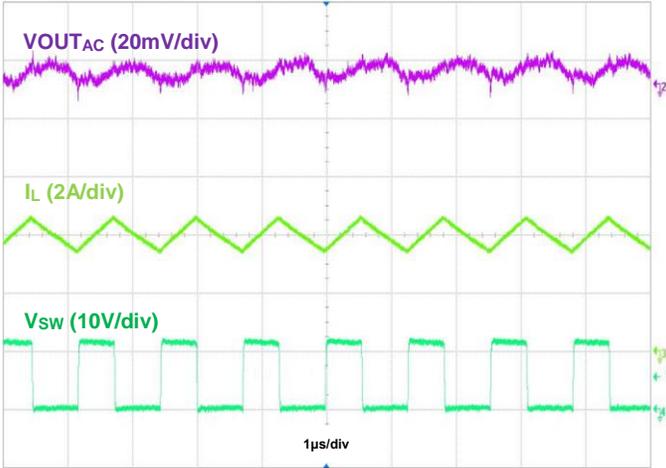


Figure 32. Output Voltage Ripple, $V_{OUT} = 5\text{V}$, $I_{OUT} = 4\text{A}$

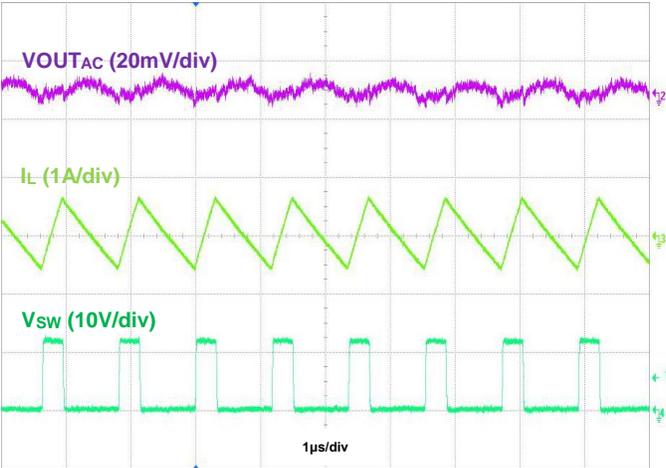


Figure 33. Output Voltage Ripple, $V_{OUT} = 3.3\text{V}$, $I_{OUT} = 50\text{mA}$

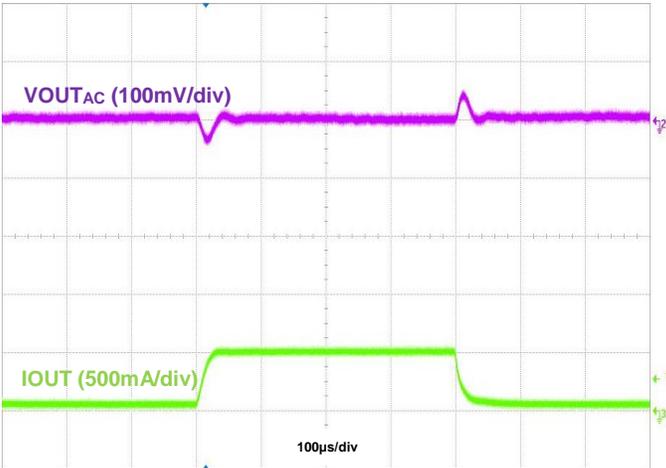


Figure 34. Load Transient, $I_{OUT} = 50\text{mA}$ to 500mA to 50mA

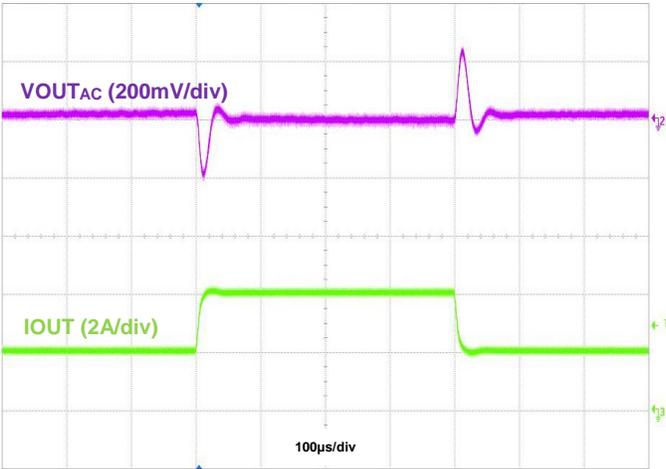


Figure 35. Load Transient, $I_{OUT} = 2\text{A}$ to 4A to 2A

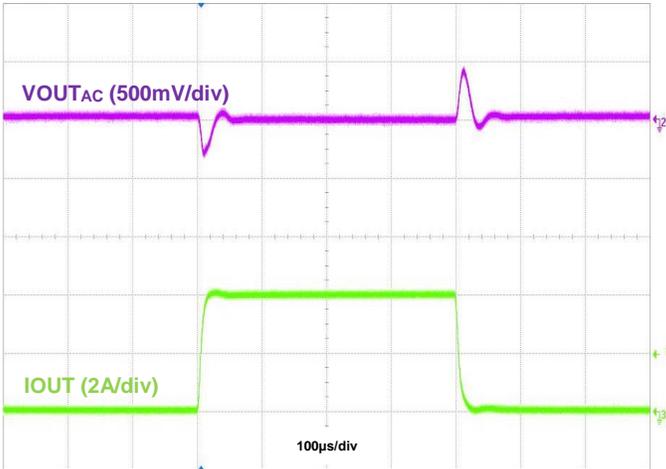


Figure 36. Load Transient, $I_{OUT} = 50\text{mA}$ to 4A to 50mA

Application Information

1. Pulse Width Modulation (PWM) Operation

The AP62400/AP62401 device is a 4.2V-to-18V input, 4A output, EMI friendly, fully integrated synchronous buck converter. Refer to the block diagram in Figure 3. The device employs constant on-time control to provide fast transient response and easy loop stabilization. At the beginning of each cycle, the one-shot pulse turns on the high-side power MOSFET, Q1, for a fixed on-time, t_{ON} . This one-shot on-pulse timing is calculated by the converter's input voltage and output voltage to maintain a pseudo-fixed frequency over the input voltage range. When Q1 is on, the inductor current rises linearly and the device charges the output capacitor. Q1 turns off after the fixed on-time expires, and the low-side power MOSFET, Q2, turns on. Once the output voltage drops below the output regulation, Q2 turns off. The one-shot timer is then reset and Q1 turns on again. The on-time is inversely proportional to the input voltage and directly proportional to the output voltage. It is calculated by the following equation:

$$t_{ON} = \frac{V_{OUT}}{V_{IN} \cdot f_{SW}} \quad \text{Eq. 1}$$

Where:

- V_{IN} is the input voltage
- V_{OUT} is the output voltage
- f_{SW} is the switching frequency

The off-time duration is t_{OFF} and starts after the on-time expires. The off-time expires when the feedback voltage decreases below the reference voltage, which then triggers the on-time duration to start again. The minimum off-time is 150ns typical.

In order to provide a small output ripple during light load conditions, the AP62401 operates in PWM regardless of output load.

2. Pulse Frequency Modulation (PFM) Operation

The AP62400 enters PFM operation at light-load conditions for high efficiency. During light-load conditions, the regulator automatically reduces the switching frequency. As the output current decreases, so too does the inductor current. The inductor current, I_L , eventually reaches 0A, marking the boundary between Continuous Conduction Mode (CCM) and Discontinuous Condition Mode (DCM). During this time, both Q1 and Q2 are off, and the load current is provided only by the output capacitor. When V_{FB} becomes lower than 0.8V, the next cycle begins, and Q1 turns on. Because the AP62400 works in PFM during light-load conditions, it can achieve power efficiency of up to 83% at a 5mA load condition.

Likewise, as the output load increases from light load to heavy load, the switching frequency increases to maintain the regulation of the output voltage. The transition point between light and heavy load conditions can be calculated using the following equation:

$$I_{LOAD} = \left(\frac{V_{IN} - V_{OUT}}{2L} \right) \cdot t_{ON} \quad \text{Eq. 2}$$

Where:

- L is the inductor value

The quiescent current of AP62400 is 190 μ A typical under a no-load, non-switching condition.

3. Enable

When disabled, the device shutdown supply current is only 1.5 μ A. When applying a voltage greater than the EN logic high threshold (typical 1.2V, rising), the AP62400/AP62401 enables all functions and the device initiates the soft-start phase. An internal 1.5 μ A pullup current source connected from the internal LDO-regulated VCC to the EN pin guarantees that if EN is left floating, the device is still automatically enabled once the voltage reaches the EN logic high threshold. The AP62400/AP62401 has a built-in 1ms soft-start time to prevent output voltage overshoot and inrush current. When the EN voltage falls below its logic low threshold (typical 1.1V, falling), the internal SS voltage discharges to ground and device operation is disabled.

The EN pin can also be used to program the undervoltage lockout thresholds. See *Undervoltage Lockout (UVLO)* section for more details.

Application Information (continued)

4. Electromagnetic Interference (EMI) Reduction with Ringing-Free Switching Node

In some applications, the system must meet EMI standards. In relation to high frequency radiation EMI noise, the switching node's (SW's) ringing amplitude is especially critical. To dampen high frequency radiated EMI noise, the AP62400/AP62401 device implements a proprietary, multi-level gate driver scheme that achieves a ringing-free switching node without sacrificing the switching node's rise and fall slew rates as well as the converter's power efficiency.

5. Adjusting Undervoltage Lockout (UVLO)

Undervoltage lockout is implemented to prevent the IC from insufficient input voltages. The AP62400/AP62401 device has a UVLO comparator that monitors the input voltage and the internal bandgap reference. The AP62400/AP62401 is disabled if the input voltage falls below 3.6V. In this UVLO event, both the high-side and low-side power MOSFETs turn off.

Some applications may desire higher VIN UVLO threshold voltages than is provided by the default setup. A 5.5µA hysteresis pullup current source on the EN pin along with an external resistive divider (R3 and R4) configures the VIN UVLO threshold voltages as shown in Figure 37.

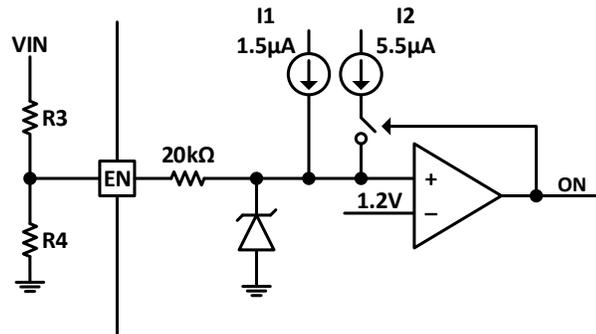


Figure 37. Programming UVLO

The resistive divider resistor values are calculated by:

$$R3 = \frac{0.917 \cdot V_{ON} - V_{OFF}}{5.625\mu A} \tag{Eq. 3}$$

$$R4 = \frac{1.1 \cdot R3}{V_{OFF} - 1.1V + 7\mu A \cdot R3} \tag{Eq. 4}$$

Where:

- V_{ON} is the rising edge VIN voltage to enable the regulator and is greater than 4.15V
- V_{OFF} is the falling edge VIN voltage to disable the regulator and is greater than 3.85V

Application Information (continued)

6. Overcurrent Protection (OCP)

The AP62400/AP62401 has cycle-by-cycle valley current limit protection by sensing the current through the internal low-side power MOSFET, Q2. While Q2 is on, the internal sensing circuitry monitors its conduction current. The overcurrent limit has a corresponding voltage limit, V_{LIMIT} . When the voltage between GND and SW is lower than V_{LIMIT} due to excessive current through Q2, the OCP is triggered, and the controller turns off Q2. During this time, both Q1 and Q2 remain off. A new switching cycle begins only when the voltage between GND and SW rises above V_{LIMIT} . If Q2 consistently hits the valley current limit for 2.5ms, the buck converter enters hiccup mode and shuts down. After 20ms of down time, the buck converter restarts powering up. Hiccup mode reduces the power dissipation in the overcurrent condition. Because the $R_{DS(ON)}$ values of the power MOSFETs increase with temperature, V_{LIMIT} has a temperature coefficient of 0.4%/°C to compensate for the temperature dependency of $R_{DS(ON)}$.

7. Thermal Shutdown (TSD)

If the junction temperature of the device reaches the thermal shutdown limit of +160°C, the AP62400/AP62401 shuts down both its high-side and low-side power MOSFETs. When the junction temperature reduces to the required level (+140°C typical), the device initiates a normal power-up cycle with soft-start.

8. Power Derating Characteristics

To prevent the regulator from exceeding the maximum recommended operating junction temperature, some thermal analysis is required. The regulator’s temperature rise is given by:

$$T_{RISE} = PD \cdot (\theta_{JA}) \tag{Eq. 5}$$

Where:

- PD is the power dissipated by the regulator
- θ_{JA} is the thermal resistance from the junction of the die to the ambient temperature

The junction temperature, T_J , is given by:

$$T_J = T_A + T_{RISE} \tag{Eq. 6}$$

Where:

- T_A is the ambient temperature of the environment

For the TSOT26 package, the θ_{JA} is 70°C/W. The actual junction temperature should not exceed the maximum recommended operating junction temperature of +125°C when considering the thermal design. Figure 38 shows a typical derating curve versus ambient temperature.

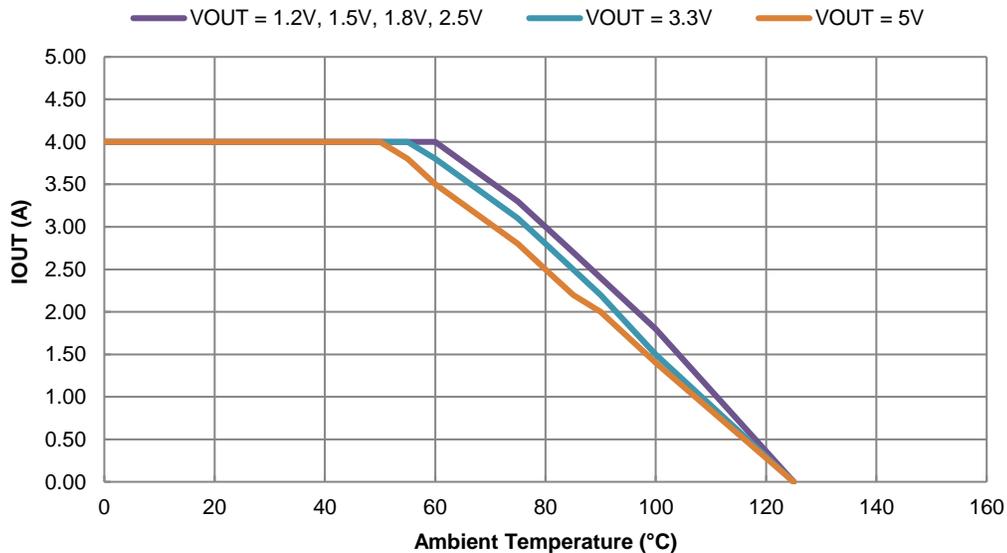


Figure 38. Output Current Derating Curve vs. Ambient Temperature, VIN = 12V

Application Information (continued)

9. Setting the Output Voltage

The AP62400/AP62401 has adjustable output voltages, starting from 0.8V, using an external resistive divider. The resistor values of the feedback network are selected based on a design trade-off between efficiency and output voltage accuracy. There is less current consumption in the feedback network for high resistor values, which improves efficiency at light loads. However, values too high cause the device to be more susceptible to noise affecting its output voltage accuracy. R1 can be determined by the following equation:

$$R1 = R2 \cdot \left(\frac{V_{OUT}}{0.8V} - 1 \right) \quad \text{Eq. 7}$$

Table 1 shows a list of recommended component selections for common AP62400/AP62401 output voltages referencing Figure 1. Consult Diodes Incorporated for other output voltage requirements.

Table 1. Recommended Component Selections

Output Voltage (V)	AP62400/AP62401						
	R1 (kΩ)	R2 (kΩ)	L (μH)	C1 (μF)	C2 (μF)	C5 (pF) Optional	C6 (nF)
1.2	4.99	10	1.0	10	2 x 22	Open	100
1.5	8.66	10	1.0	10	2 x 22	Open	100
1.8	12.4	10	1.5	10	2 x 22	10 - 100	100
2.5	21.5	10	1.5	10	2 x 22	10 - 100	100
3.3	31.6	10	2.2	10	2 x 22	10 - 100	100
5.0	52.3	10	2.2	10	2 x 22	10 - 100	100

10. Inductor

Calculating the inductor value is a critical factor in designing a buck converter. For most designs, the following equation can be used to calculate the inductor value:

$$L = \frac{V_{OUT} \cdot (V_{IN} - V_{OUT})}{V_{IN} \cdot \Delta I_L \cdot f_{SW}} \quad \text{Eq. 8}$$

Where:

- ΔI_L is the inductor current ripple
- f_{SW} is the buck converter switching frequency

For AP62400/AP62401, choose ΔI_L to be 30% to 50% of the maximum load current of 4A.

The inductor peak current is calculated by:

$$I_{LPEAK} = I_{LOAD} + \frac{\Delta I_L}{2} \quad \text{Eq. 9}$$

Peak current determines the required saturation current rating, which influences the size of the inductor. Saturating the inductor decreases the converter efficiency while increasing the temperatures of the inductor and the internal power MOSFETs. Therefore, choosing an inductor with the appropriate saturation current rating is important. For most applications, it is recommended to select an inductor of approximately 1.0μH to 3.3μH with a DC current rating of at least 35% higher than the maximum load current. For highest efficiency, the inductor's DC resistance should be less than 30mΩ. Use a larger inductance for improved efficiency under light-load conditions.

Application Information (continued)

11. Input Capacitor

The input capacitor reduces both the surge current drawn from the input supply as well as the switching noise from the device. The input capacitor must sustain the ripple current produced during the on-time of Q1. It must have a low ESR to minimize power dissipation due to the RMS input current.

The RMS current rating of the input capacitor is a critical parameter and must be higher than the RMS input current. As a rule of thumb, select an input capacitor with an RMS current rating greater than half of the maximum load current.

Due to large di/dt through the input capacitor, electrolytic or ceramic capacitors with low ESR should be used. If using a tantalum capacitor, it must be surge protected or else capacitor failure could occur. Using a ceramic capacitor of 10 μ F or greater is sufficient for most applications.

12. Output Capacitor

The output capacitor keeps the output voltage ripple small, ensures feedback loop stability, and reduces both the overshoots and undershoots of the output voltage during load transients. During the first few microseconds of an increasing load transient, the converter recognizes the change from steady-state and sets the off-time to minimum to supply more current to the load. However, the inductor limits the change to increasing current depending on its inductance. Therefore, the output capacitor supplies the difference in current to the load during this time. Likewise, during the first few microseconds of a decreasing load transient, the converter recognizes the change from steady-state and increases the off-time to reduce the current supplied to the load. However, the inductor limits the change in decreasing current as well. Therefore, the output capacitor absorbs the excess current from the inductor during this time.

The effective output capacitance, C_{OUT} , requirements can be calculated from the equations below.

The ESR of the output capacitor dominates the output voltage ripple. The amount of ripple can be calculated by:

$$V_{OUT_{Ripple}} = \Delta I_L \cdot \left(ESR + \frac{1}{8 \cdot f_{sw} \cdot C_{OUT}} \right) \quad \text{Eq. 10}$$

Output capacitors with large capacitance and low ESR are the best option. For most applications, a total capacitance of 2 x 22 μ F using ceramic capacitors is sufficient. To meet the load transient requirements, the calculated C_{OUT} should satisfy the following inequality:

$$C_{OUT} > \max \left(\frac{L \cdot I_{Trans}^2}{\Delta V_{Overshoot} \cdot V_{OUT}}, \frac{L \cdot I_{Trans}^2}{\Delta V_{Undershoot} \cdot (V_{IN} - V_{OUT})} \right) \quad \text{Eq. 11}$$

Where:

- I_{Trans} is the load transient
- $\Delta V_{Overshoot}$ is the maximum output overshoot voltage
- $\Delta V_{Undershoot}$ is the maximum output undershoot voltage

13. Bootstrap Capacitor

To ensure proper operation, a ceramic capacitor must be connected between the BST and SW pins to supply the drive voltage for the high-side power MOSFET. A 100nF ceramic capacitor is sufficient.

Layout

PCB Layout

1. The AP62400/AP62401 works at 4A load current so heat dissipation is a major concern in the layout of the PCB. 2oz copper for both the top and bottom layers is recommended.
2. Place the input capacitors as closely across VIN and GND as possible.
3. Place the inductor as close to SW as possible.
4. Place the output capacitors as close to GND as possible.
5. Place the feedback components as close to FB as possible.
6. If using four or more layers, use at least the 2nd and 3rd layers as GND to maximize thermal performance.
7. Add as many vias as possible around both the GND pin and under the GND plane for heat dissipation to all the GND layers.
8. Add as many vias as possible around both the VIN pin and under the VIN plane for heat dissipation to all the VIN layers.
9. See Figure 39 for more details.

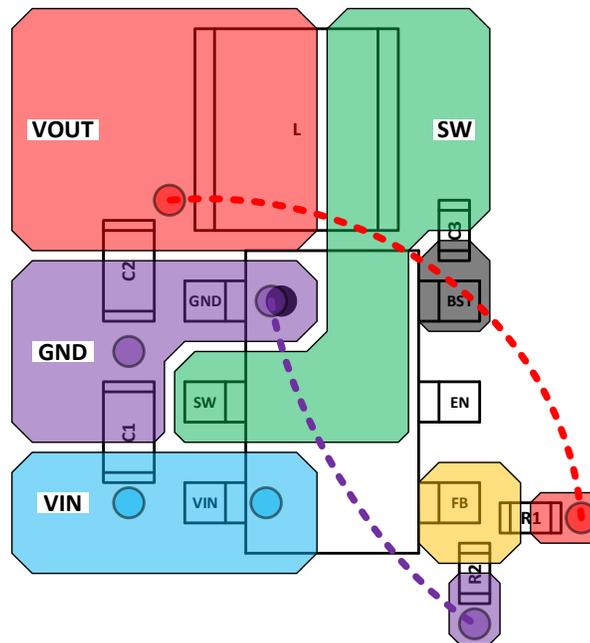
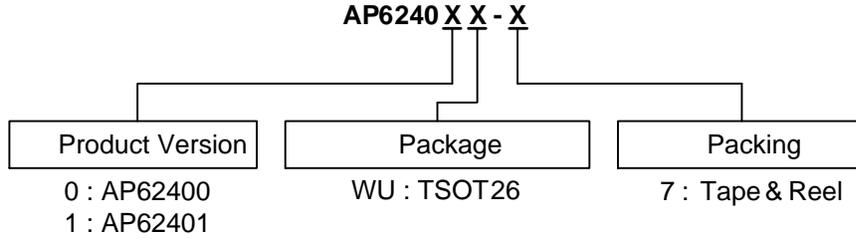


Figure 39. Recommended PCB Layout, TSOT26 Package

Ordering Information



Part Number	Operation Mode	V _{FB} (V)	Package	Package Code	Packing	
					Qty.	Carrier
AP62400WU-7	PFM/PWM	0.800	TSOT26	WU	3,000	-7 Tape and Reel
AP62401WU-7	PWM Only	0.800	TSOT26	WU	3,000	-7 Tape and Reel

Marking Information

TSOT26

(Top View)

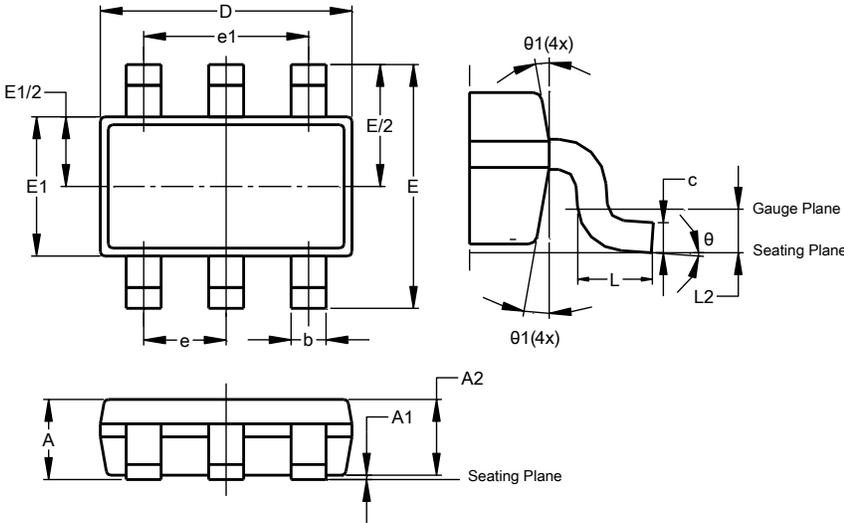
XX : Identification Code
Y : Year 0 to 9 (ex: 3 = 2023)
W : Week : A to Z : week 1 to 26
a to z : week 27 to 52; z represents week 52 and 53
X : Internal Code

Part Number	Package	Identification Code
AP62400WU-7	TSOT26	DA
AP62401WU-7	TSOT26	DB

Package Outline Dimensions

Please see <http://www.diodes.com/package-outlines.html> for the latest version.

TSOT26

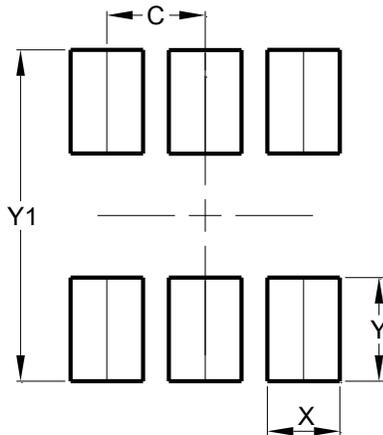


TSOT26			
Dim	Min	Max	Typ
A	-	1.00	-
A1	0.010	0.100	-
A2	0.840	0.900	-
D	2.800	3.000	2.900
E	2.800 BSC		
E1	1.500	1.700	1.600
b	0.300	0.450	-
c	0.120	0.200	-
e	0.950 BSC		
e1	1.900 BSC		
L	0.30	0.50	-
L2	0.250 BSC		
θ	0°	8°	4°
θ1	4°	12°	-
All Dimensions in mm			

Suggested Pad Layout

Please see <http://www.diodes.com/package-outlines.html> for the latest version.

TSOT26



Dimensions	Value (in mm)
C	0.950
X	0.700
Y	1.000
Y1	3.200

Mechanical Data

TSOT26

- Moisture Sensitivity: Level 1 per J-STD-020
- Terminals: Finish – Matte Tin Plated Leads, Solderable per MIL-STD-202, Method 208 ③
- Weight: 0.0145 grams (Approximate)

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