### Product datasheet **Characteristics**

### **ATV71HU15S6X**





### Main

Main				
Range of product	Altivar 71			
Product or component type	Variable speed drive			
Product specific application	Complex, high-power machines			
Component name	ATV71			
Motor power kW	1.5 kWat 500 V 3 phases			
Motor power hp	2 hpat 575 V 3 phases			
Motor cable length				
[Us] rated supply voltage	500600 V (- 1510 %)			
Phase	3 phases			
Line current	5.6 Afor 500 V 3 phases 1.5 kW / 2 hp 4.9 Afor 600 V 3 phases 1.5 kW / 2 hp			
EMC filter	Without EMC filter			
Assembly style	With heat sink			
Variant	Built-in unit with forced cooling			
Prospective line Isc	22 kA, 3 phases			
Nominal output current	3.2 Aat 4 kHz 500 V 3 phases 1.5 kW / 2 hp 2.7 Aat 4 kHz 575 V 3 phases 1.5 kW / 2 hp			
Maximum transient current	4.8 Afor 60 s 3 phases 1.5 kW / 2 hp 5.3 Afor 2 s 3 phases 1.5 kW / 2 hp			
Output frequency	0.1500 Hz			
Nominal switching frequency	4 kHz			
Switching frequency	2.56 kHz adjustable 46 kHz with derating factor			
Asynchronous motor control profile	Voltage/frequency ratio, 2 points Voltage/frequency ratio, 5 points Flux vector control without sensor, standard Voltage/frequency ratio - Energy Saving, quadratic U/f Flux vector control without sensor, ENA (energy Adaptation) system Flux vector control without sensor, 2 points Flux vector control with sensor, standard			
Type of polarization	No impedance Modbus			

#### Complementary

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Product destination	Asynchronous motors Synchronous motors
Supply voltage limits	425660 V
Supply frequency	5060 Hz (+/-5 %)
Network frequency	47.563 Hz
Speed range	1100 in open-loop mode, without speed feedback
Speed accuracy	+/- 10 % of nominal slip 0.2 Tn to Tn torque variation without speed feedback
Torque accuracy	+/- 15 % in open-loop mode, without speed feedback
Transient overtorque	170 % of nominal motor torque +/- 10 %for 60 s 220 % of nominal motor torque +/- 10 %for 2 s
Braking torque	30 % without braking resistor <= 125 % with braking resistor
Synchronous motor control profile	Vector control without sensor, standard Vector control with sensor, standard
Regulation loop	Frequency PI regulator
Motor slip compensation	Adjustable



	Automatic whatever the load Can be suppressed Not available in voltage/frequency ratio (2 or 5 points)
Local signalling	LCD display unit presence of operation function, status and configuration
Output voltage	<= power supply voltage
Insulation	Electrical between power and control
Type of cable	With an IP21 or an IP31 kit: 3-strand IEC cableat 104 °F (40 °C), copper 70 °C PVC Without mounting kit: 1-strand IEC cableat 113 °F (45 °C), copper 70 °C PVC Without mounting kit: 1-strand IEC cableat 113 °F (45 °C), copper 90 °C XLPE/EPR With UL Type 1 kit: 3-strand UL 508 cableat 104 °F (40 °C), copper 75 °C PVC
Electrical connection	Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B, Ll1Ll6, PWR terminal 2.5 mm <sup>2</sup> / AWG 14 L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB terminal 16 mm <sup>2</sup> / AWG 4
Tightening torque	L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB 26.55 lbf.in (3 N.m) / 26.5 lb.in Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B, Ll1Ll6, PWR 5.31 lbf.in (0.6 N.m)
Supply	Internal supply for reference potentiometer (1 to 10 kOhm), 10.5 V DC +/- 5 %, <= 10 mAfor overload and short-circuit protection Internal supply, 24 V DC, voltage limits 2127 V, <= 200 mAfor overload and short-circuit protection External supply, 24 V DC, voltage limits 1930 V
Analogue input number	2
Analogue input type	Al1-/Al1+ bipolar differential voltage +/- 10 V DC, input voltage 24 V max, resolution 11 bits + sign Al2 software-configurable current 020 mA, impedance 242 Ohm, resolution 11 bits Al2 software-configurable voltage 010 V DC, input voltage 24 V max, impedance 30000 Ohm, resolution 11 bits
Sampling duration	Al1-/Al1+ 2 ms, +/- 0.5 ms analog input(s) Al2 2 ms, +/- 0.5 ms analog input(s) Ll1Ll5 2 ms, +/- 0.5 ms discrete input(s) Ll6 (if configured as logic input) 2 ms, +/- 0.5 ms discrete input(s) AO1 2 ms, +/- 0.5 ms analog input(s)
Response time	<= 100 ms in STO (Safe Torque Off) R1A, R1B, R1C <= 7 ms, tolerance +/- 0.5 ms R2A, R2B <= 7 ms, tolerance +/- 0.5 ms
Accuracy	AI1-/AI1+ +/- 0.6 % for a temperature variation 60 °C AI2 +/- 0.6 % for a temperature variation 60 °C AO1 +/- 1 % for a temperature variation 60 °C
Linearity error	Al1-/Al1+ +/- 0.15 % of maximum value Al2 +/- 0.15 % of maximum value AO1 +/- 0.2 %
Analogue output number	1
Analogue output type	AO1 software-configurable current 020 mA, impedance 500 Ohm, resolution 10 bits AO1 software-configurable logic output 10 V <= 20 mA AO1 software-configurable voltage 010 V DC, impedance 470 Ohm, resolution 10 bits
Discrete output number	2
Discrete output type	R1A, R1B, R1C configurable relay logic NO/NC, electrical durability 100000 cycles R2A, R2B configurable relay logic NO, electrical durability 100000 cycles
Minimum switching current	Configurable relay logic 3 mAat 24 V DC
Maximum switching current	R1, R2 on resistive load, 5 Aat 250 V AC, cos phi = 1, R1, R2 on resistive load, 5 Aat 30 V DC, cos phi = 1, R1, R2 on inductive load, 2 Aat 250 V AC, cos phi = $0.4$ , R1, R2 on inductive load, 2 Aat 30 V DC, cos phi = $0.4$ ,
Discrete input number	7
Discrete input type	LI6: switch-configurable 24 V DC with level 1 PLC, impedance: 3500 Ohm PWR: safety input 24 V DC, impedance: 1500 Ohm conforming to ISO 13849-1 level d LI1LI5: programmable 24 V DC with level 1 PLC, impedance: 3500 Ohm
Discrete input logic	LI6: switch-configurable PTC probe 06, impedance: 1500 Ohm      LI1LI5 positive logic (source), < 5 V (state 0), > 11 V (state 0)      LI1LI5 negative logic (sink), > 16 V (state 0), < 10 V (state 0)
Acceleration and deceleration ramps	Automatic adaptation of ramp if braking capacity exceeded, by using resistor Linear adjustable separately from 0.01 to 9000 s S, U or customized
Braking to standstill	By DC injection



Protection type	Drive against exceeding limit speed Drive against input phase loss Drive break on the control circuit Drive input phase breaks Drive line supply overvoltage Drive line supply undervoltage Drive overcurrent between output phases and earth Drive overheating protection Drive overheating protection Drive overvoltages on the DC bus Drive power removal Drive short-circuit between motor phases Drive thermal protection Motor motor phase break Motor power removal Motor thermal protection
Insulation resistance	> 1 mOhm at 500 V DC for 1 minute to earth
Frequency resolution	Analog input 0.024/50 Hz Display unit 0.1 Hz
Communication port protocol	CANopen Modbus
Connector type	1 RJ45 Modbus on front face 1 RJ45 Modbus on terminal 1 RJ45 CANopen
Physical interface	2-wire RS 485 Modbus
Transmission frame	RTU Modbus
Transmission rate	20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps CANopen 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps Modbus on terminal 9600 bps, 19200 bps Modbus on front face
Data format	8 bits, 1 stop, even parity Modbus on front face 8 bits, odd even or no configurable parity Modbus on terminal
Number of addresses	1247 Modbus 1127 CANopen
Method of access	Slave CANopen
Marking	CE
Operating position	Vertical +/- 10 degree
Height	11.61 in (295 mm)
Depth	8.39 in (213 mm)
Width	8.27 in (210 mm)
Product weight	16.53 lb(US) (7.5 kg)
Option card	APOGEE FLN communication card BACnet communication card CC-Link communication card Controller inside programmable card DeviceNet communication card Ethernet/IP communication card Fipio communication card I/O extension card Interbus-S communication card LonWorks communication card METASYS N2 communication card Modbus Plus communication card Modbus TCP communication card Profibus DP communication card Profibus DP V1 communication card

#### Environment

noise level	60.2 dB conforming to 86/188/EEC				
dielectric strength	5092 V DC between control and power terminals 3800 V DC between earth and power terminals				
electromagnetic compatibility	Conducted radio-frequency immunity test conforming to IEC 61000-4-6 level 3 Electrical fast transient/burst immunity test conforming to IEC 61000-4-4 level 4 Electrostatic discharge immunity test conforming to IEC 61000-4-2 level 3 Radiated radio-frequency electromagnetic field immunity test conforming to IEC 61000-4-3 level 3 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 1.2/50 µs - 8/20 µs surge immunity test conforming to IEC 61000-4-5 level 3				
standards	EN 55011 group 1 class B EN/IEC 61800-3				



	EN/IEC 61800-3 environment 1 EN/IEC 61800-3 environment 2 EN/IEC 61800-5-1 IEC 60721-3-3 class 3C1 IEC 60721-3-3 class 3S2 UL Type 1
product certifications	CSA C-Tick GOST NOM 117 UL
pollution degree	3 conforming to EN/IEC 61800-5-1 3 conforming to UL 840
IP degree of protection	IP20 on upper part without blanking plate on cover conforming to EN/IEC 60529 IP20 on upper part without blanking plate on cover conforming to EN/IEC 61800-5-1 IP21 conforming to EN/IEC 60529 IP21 conforming to EN/IEC 61800-5-1 IP41 on upper part conforming to EN/IEC 60529 IP41 on upper part conforming to EN/IEC 61800-5-1 IP54 on lower part conforming to EN/IEC 60529 IP54 on lower part conforming to EN/IEC 61800-5-1
vibration resistance	1.5 mm peak to peak (f = 313 Hz) conforming to EN/IEC 60068-2-6 1 gn (f = 13200 Hz) conforming to EN/IEC 60068-2-6
shock resistance	15 gn 11 ms conforming to EN/IEC 60068-2-27
relative humidity	595 % without condensation conforming to IEC 60068-2-3 595 % without dripping water conforming to IEC 60068-2-3
ambient air temperature for operation	14122 °F (-1050 °C) without derating 122140 °F (5060 °C) with derating factor
ambient air temperature for storage	-13158 °F (-2570 °C)
operating altitude	<= 3280.84 ft (1000 m) without derating 3280.847414.7 ft (10002260 m) with current derating 1 % per 100 m

#### **Offer Sustainability**

Green Premium product	Green Premium product
Compliant - since 1601 - Schneider Electric declaration of conformity	Compliant - since 1601 - Schneider Electric declaration of conformity
Reference contains SVHC above the threshold - go to CaP for more details	Reference contains SVHC above the threshold
Available	Available
Available	Available
WARNING: This product can expose you to chemicals including:	WARNING: This product can expose you to chemicals including:
Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm.	Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm.
For more information go to www.p65warnings.ca.gov	For more information go to www.p65warnings.ca.gov

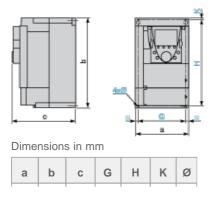
#### Contractual warranty

Warranty period

18 months

### UL Type 1/IP 20 Drives

#### **Dimensions without Option Card**



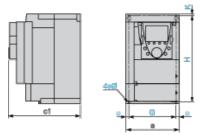


210 295 213 190 283 6 6

Dimensions in in.

а	b	с	G	Н	К	Ø
8.26	11.61	8.38	7.48	11.14	0.23	0.23

#### Dimensions with 1 Option Card (1)



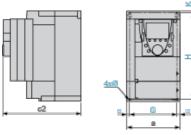
Dimensions in mm

а	c1	G	н		к	ø		
210	236	190	283	3	6	6		
Dimensions in in.								
2			C		ц	ĸ		

а	c1	G	Н	K	Ø
8.26	9.29	7.48	11.14	0.23	0.23

(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

#### Dimensions with 2 Option Cards (1)



Dimensions in mm

а	c2	G	Н	к	ø			
210	259	190	283	6	6			
Dimensions in in.								

а	c2	G	Н	К	ø
8.26	10.20	7.48	11.14	0.23	0.23

(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

#### **Mounting Recommendations**

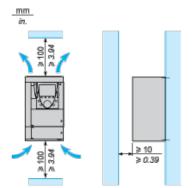
Depending on the conditions in which the drive is to be used, its installation will require certain precautions and the use of appropriate accessories.

Install the unit vertically:

- Avoid placing it close to heating elements
- Leave sufficient free space to ensure that the air required for cooling purposes can circulate from the bottom to the top of the unit.

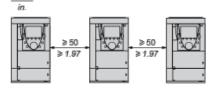
#### Clearance



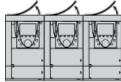


#### Mounting Types

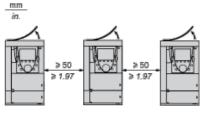
Type A Mounting



Type B Mounting



Type C Mounting



By removing the protective blanking cover from the top of the drive, the degree of protection for the drive becomes IP 20. The protective blanking cover may vary according to the drive model (refer to the user guide).

The protective blanking cover must be removed from ATV 71P•••N4Z drives when they are mounted in a dust and damp proof enclosure.

#### **Mounting and Temperature Conditions**

#### Mounting type A and B

The drive can operate with a switching frequency 2,5...6 kHz up to 50°C without derating.

#### Mounting type C

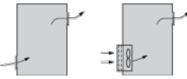
The drive can operate with a switching frequency 2,5...6 kHz up to 60°C without derating. For operation above 50°C (122°F), power supply voltage must be limited up to 600 V +5%.

#### Specific Recommendations for Mounting the Drive in an Enclosure

#### Ventilation

To ensure proper air circulation in the drive:

- Fit ventilation grilles.
- Ensure that there is sufficient ventilation. If there is not, install a forced ventilation unit with a filter. The openings and/or fans must provide a flow rate at least equal to that of the drive fans (refer to the product characteristics).



Use special filters with IP 54 protection.



Remove the blanking cover from the top of the drive.

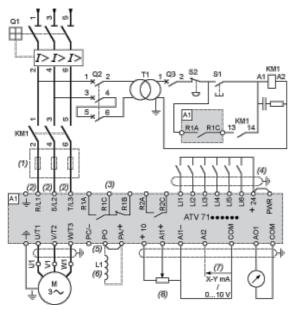
#### Dust and Damp Proof Metal Enclosure (IP 54)

The drive must be mounted in a dust and damp proof enclosure in certain environmental conditions: dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc.

This enables the drive to be used in an enclosure where the maximum internal temperature reaches 50°C.

# Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

#### Three-Phase Power Supply with Upstream Breaking via Contactor



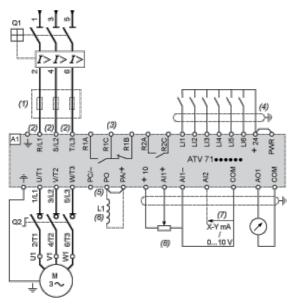
- A1 ATV71 drive
- KM1 Contactor
- L1 DC choke
- Q1 Circuit-breaker
- Q2 GV2 L rated at twice the nominal primary current of T1
- Q3 GB2CB05
- S1, XB4 B or XB5 A pushbuttons
- S2
- T1 100 VA transformer 220 V secondary
- (1) Line choke (three-phase); mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (2) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (3) Fault relay contacts. Used for remote signalling of the drive status.
- (4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (5) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (6) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

# Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply with Downstream Breaking via Switch Disconnector



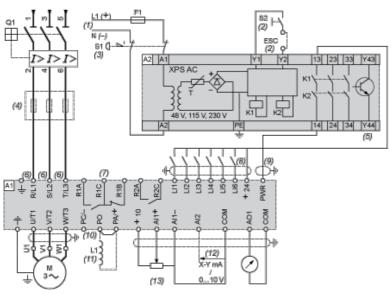


- A1 ATV71 drive
- L1 DC choke
- Q1 Circuit-breaker
- Q2 Switch disconnector (Vario)
- (1) Line choke (three-phase), mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (2) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (3) Fault relay contacts. Used for remote signalling of the drive status.
- (4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (5) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (6) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

## Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 0 According to IEC/EN 60204-1

#### Three-Phase Power Supply, Low Inertia Machine, Vertical Movement



A1 ATV71 drive

A2 Preventa XPS AC safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" function for several drives on the same machine. In this case, each drive must connect its PWR terminal to its + 24 V via



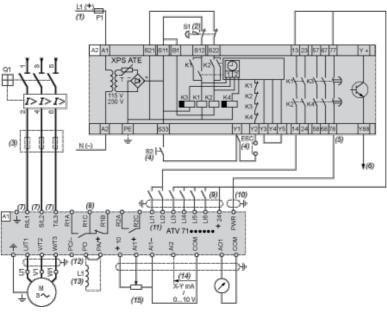
the safety contacts on the XPS AC module. These contacts are independent for each drive.

- F1 Fuse
- L1 DC choke
- Q1 Circuit-breaker
- S1 Emergency stop button with 2 contacts
- S2 XB4 B or XB5 A pushbutton
- (1) Power supply: 24 Vdc or Vac, 48 Vac, 115 Vac, 230 Vac.
- (2) S2: resets XPS AC module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- (3) Requests freewheel stopping of the movement and activates the "Power Removal" safety function.
- (4) Line choke (three-phase), mandatory for and ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (5) The logic output can be used to signal that the machine is in a safe stop state.
- (6) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (7) Fault relay contacts. Used for remote signalling of the drive status.
- (8) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (9) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm /0.09 in., maximum length 15 m / 49.21 ft. The cable shielding must be earthed.
- (10) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (11) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (12) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (13) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

# Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 1 According to IEC/EN 60204-1

#### Three-Phase Power Supply, High Inertia Machine



- A1 ATV71 drive
- A2 Preventa XPS ATE safety module for monitoring emergency stops and switches. One safety module can manage the "Power
  (5) Removal" safety function for several drives on the same machine. In this case the time delay must be adjusted on the drive controlling the motor that requires the longest stopping time. In addition, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS ATE module. These contacts are independent for each drive.
- F1 Fuse
- L1 DC choke
- Q1 Circuit-breaker
- **S1** Emergency stop button with 2 N/C contacts
- S2 Run button
- (1) Power supply: 24 Vdc or Vac, 115 Vac, 230 Vac.



- (2) Requests controlled stopping of the movement and activates the "Power Removal" safety function.
- (3) Line choke (three-phase), mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (4) S2: resets XPS ATE module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- (5) For stopping times requiring more than 30 seconds in category 1, use a Preventa XPS AV safety module which can provide a maximum time delay of 300 seconds.
- (6) The logic output can be used to signal that the machine is in a safe state.
- (7) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (8) Fault relay contacts. Used for remote signalling of the drive status.
- (9) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (10) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm/0.09 in., maximum length 15 m/49.21 ft. The cable shielding must be earthed.
- (11) Logic inputs Ll1 and Ll2 must be assigned to the direction of rotation: Ll1 in the forward direction and Ll2 in the reverse direction.
- (12) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (13) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (14) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (15) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.



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Authorized Distributor

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