

Rochester Electronics Manufactured Components

Rochester branded components are manufactured using either die/wafers purchased from the original suppliers or Rochester wafers recreated from the original IP. All recreations are done with the approval of the OCM.

Parts are tested using original factory test programs or Rochester developed test solutions to guarantee product meets or exceed the OCM data sheet.

Quality Overview

- ISO-9001
- AS9120 certification
- Qualified Manufacturers List (QML) MIL-PRF-35835
 - Class Q Military
 - Class V Space Level
- Qualified Suppliers List of Distributors (QSLD)
- Rochester is a critical supplier to DLA and meets all industry and DLA standards.

Rochester Electronics, LLC is committed to supplying products that satisfy customer expectations for quality and are equal to those originally supplied by industry manufacturers.

The original manufacturer's datasheet accompanying this document reflects the performance and specifications of the Rochester manufactured version of this device. Rochester Electronics guarantees the performance of its semiconductor products to the original OEM specifications. 'Typical' values are for reference purposes only. Certain minimum or maximum ratings may be based on product characterization, design, simulation, or sample testing.

Universal 4-Bit Shift Register

The SN74LS195A is a high speed 4-Bit Shift Register offering typical shift frequencies of 39 MHz. It is useful for a wide variety of register and counting applications. It utilizes the Schottky diode clamped process to achieve high speeds and is fully compatible with all ON Semiconductor TTL products.

- Typical Shift Right Frequency of 39 MHz
- Asynchronous Master Reset
- J, K Inputs to First Stage
- Fully Synchronous Serial or Parallel Data Transfers
- Input Clamp Diodes Limit High Speed Termination Effects

GUARANTEED OPERATING RANGES

Symbol Parameter		Min	Тур	Max	Unit
V _{CC}	Supply Voltage	4.75	5.0	5.25	V
T _A	Operating Ambient Temperature Range	0	25	70	°C
I _{OH}	Output Current - High			-0.4	mA
I _{OL}	Output Current - Low			8.0	mA



ON Semiconductor™

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LOW
POWER
SCHOTTKY



PLASTIC N SUFFIX CASE 648



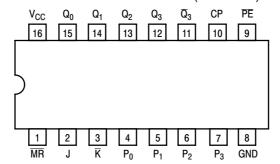
SOIC D SUFFIX CASE 751B

ORDERING INFORMATION

		I	
Device	Package	Shipping	
SN74LS195AN	16 Pin DIP	2000 Units/Box	
SN74LS195AD	SOIC-16	38 Units/Rail	
SN74LS195ADR2	SOIC-16	2500/Tape & Reel	

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CONNECTION DIAGRAM DIP (TOP VIEW)



NOTE:

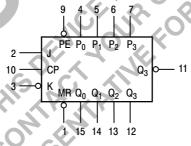
The Flatpak version has the same pinouts (Connection Diagram) as the Dual In-Line Package.

	_	LOADING	(Note a)
PIN NAMES		HIGH	LOW
PE	Parallel Enable (Active LOW) Input	0.5 U.L.	0.25 U.L.
P ₀ - P ₃	Parallel Data Inputs	0.5 U.L.	0.25 U.L.
J	First Stage J (Active HIGH) Input	0.5 U.L.	0.25 U.L.
K	First Stage K (Active LOW) Input	0.5 U.L.	0.25 U.L.
CP	Clock (Active HIGH Going Edge) Input	0.5 U.L.	0.25 U.L.
MR	Master Reset (Active LOW) Input	0.5 U.L.	0.25 U.L.
$Q_0 - Q_3$	Parallel Outputs	10 U.L.	5 U.L.
\overline{Q}_3	Complementary Last Stage Output	10 U.L.	5 U.L.

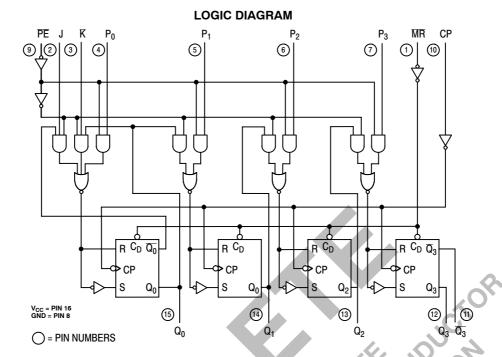
NOTES:

a) 1 TTL Unit Load (U.L.) = 40 μA HIGH/1.6 mA LOW.

LOGIC SYMBOL



V_{CC} = PIN 16



FUNCTIONAL DESCRIPTION

The Logic Diagram and Truth Table indicate the functional characteristics of the LS195A 4-Bit Shift Register. The device is useful in a wide variety of shifting, counting and storage applications. It performs serial, parallel, serial to parallel, or parallel to serial data transfers at very high speeds.

The LS195A has two primary modes of operation, shift right $(Q_0 \rightarrow Q_1)$ and parallel load which are controlled by the state of the Parallel Enable (\overline{PE}) input. When the PE input is HIGH, serial data enters the first flip-flop Q_0 via the J and \overline{K} inputs and is shifted one bit in the direction $Q_0 \rightarrow Q_1 \rightarrow Q_2 \rightarrow \overline{Q}_3$ following each LOW to HIGH clock transition. The \overline{JK} inputs provide the flexibility of the JK type input for special applications, and the simple D type input for general applications by tying the two pins together. When the \overline{PE}

input is LOW, the LS195A appears as four common clocked D flip-flops. The data on the parallel inputs P_0 , P_1 , P_2 , P_3 is transferred to the respective Q_0 , Q_1 , Q_2 , Q_3 outputs following the LOW to HIGH clock transition. Shift left operations $(Q_3 \rightarrow \square Q_2)$ can be achieved by tying the Q_n Outputs to the P_{n-1} inputs and holding the \overline{PE} input LOW.

All serial and parallel data transfers are synchronous, occurring after each LOW to HIGH clock transition. Since the LS195A utilizes edge-triggering, there is no restriction on the activity of the J, \overline{K} , P_n and \overline{PE} inputs for logic operation — except for the set-up and release time requirements.

A LOW on the asynchronous Master Reset (\overline{MR}) input sets all Q outputs LOW, independent of any other input condition.

MODE	SFL	FCT —	TRUT	H TABL	F

OPERATING MODES	INPUTS					OUTPUTS				
OPERATING MODES	MR	PE	J	K	P _n	Q_0	Q ₁	Q_2	Q ₃	\overline{Q}_3
Asynchronous Reset	L	Х	Х	Х	Х	L	L	L	L	Н
Shift, Set First Stage	Н	h	h	h	Χ	Н	q_0	q ₁	q_2	\overline{q}_2
Shift, Reset First	Н	h	1	- 1	Х	L	q_0	q_1	q_2	\overline{q}_2
Shift, Toggle First Stage	Н	h	h	- 1	Х	\overline{q}_0	q_0	q_1	q_2	\overline{q}_2
Shift, Retain First Stage	Н	h	I	h	Χ	q_0	q_0	q ₁	q_2	\overline{q}_2
Parallel Load	Н	I	Х	Х	p _n	p ₀	p ₁	p ₂	p ₃	_ p ₃

L = LOW voltage levels

H = HIGH voltage levels

X = Don't Care

I = LOW voltage level one set-up time prior to the LOW to HIGH clock transition.

h = HIGH voltage level one set-up time prior to the LOW to HIGH clock transition.

 p_n (q_n) = Lower case letters indicate the state of the referenced input (or output) one set-up time prior to the LOW to HIGH clock transition.

DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE (unless otherwise specified)

			Limits				
Symbol	Parameter	Min	Тур	Max	Unit	Tes	t Conditions
V _{IH}	Input HIGH Voltage	2.0			V	Guaranteed Input HIGH Voltage for All Inputs	
V _{IL}	Input LOW Voltage			0.8	V	Guaranteed Input LOW Voltage for All Inputs	
V _{IK}	Input Clamp Diode Voltage		-0.65	-1.5	V	V _{CC} = MIN, I _{IN} = –18 mA	
V _{OH}	Output HIGH Voltage	2.7	3.5		V	V_{CC} = MIN, I_{OH} = MAX, V_{IN} = V_{IH} or V_{IL} per Truth Table	
.,	0 1- 11 0000/100-		0.25	0.4	V	I _{OL} = 4.0 mA	V _{CC} = V _{CC} MIN,
V _{OL}	Output LOW Voltage		0.35	0.5	V	I _{OL} = 8.0 mA	V _{IN} = V _{IL} or V _{IH} per Truth Table
,	Innert HCH Correct			20	μΑ	V _{CC} = MAX, V _{IN} :	= 2.7 V
I _{IH}	Input HIGH Current			0.1	mA	V _{CC} = MAX, V _{IN} = 7.0 V	
I _{IL}	Input LOW Current			-0.4	mA	V _{CC} = MAX, V _{IN} = 0.4 V	
Ios	Short Circuit Current (Note 1)	-20		-100	mA	V _{CC} = MAX	
Icc	Power Supply Current			21	mA	V _{CC} = MAX	10

Note 1: Not more than one output should be shorted at a time, nor for more than 1 second.

AC CHARACTERISTICS (T_A = 25°C)

			Limits			Y.C. 67.
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
f _{MAX}	Maximum Clock Frequency	30	39	~	MHz	
t _{PLH} t _{PHL}	Propagation Delay, Clock to Output		14 17	22 26	ns	V _{CC} = 5.0 V C _L = 15 pF
t _{PHL}	Propagation Delay, MR to Output		19	30	ns	

AC SETUP REQUIREMENTS $(T_A = 25^{\circ}C)$

		O	Limits	11		
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
t _W	CP Clock Pulse Width	16	1		ns	
t _W	MR Pulse Width	12			ns	
t _s	PE Setup Time	25			ns	
t _s	Data Setup Time	15			ns	V _{CC} = 5.0 V
t _{rec}	Recovery Time	25			ns	
t _{rel}	PE Release Time			10	ns	
t _h	Data Hold Time	0			ns	

DEFINITIONS OF TERMS

SETUP $TIME(t_s)$ —is defined as the minimum time required for the correct logic level to be present at the logic input prior to the clock transition from LOW to HIGH in order to be recognized and transferred to the outputs.

HOLD TIME (t_h) — is defined as the minimum time following the clock transition from LOW to HIGH that the logic level must be maintained at the input in order to ensure

continued recognition. A negative HOLD TIME indicates that the correct logic level may be released prior to the clock transition from LOW to HIGH and still be recognized.

RECOVERY TIME (t_{rec}) — is defined as the minimum time required between the end of the reset pulse and the clock transition from LOW to HIGH in order to recognize and transfer HIGH Data to the Q outputs.

AC WAVEFORMS

The shaded areas indicate when the input is permitted to change for predictable output performance.

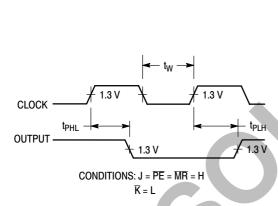


Figure 1. Clock to Output Delays and Clock Pulse Width

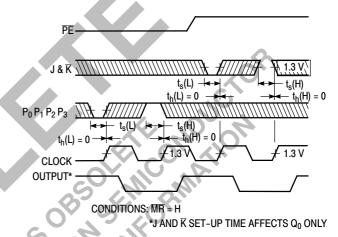


Figure 3. Setup (t_s) and Hold (t_h) Time for Serial Data (J & K) and Parallel Data (P_0, P_1, P_2, P_3)

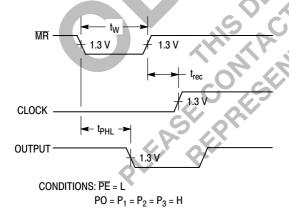
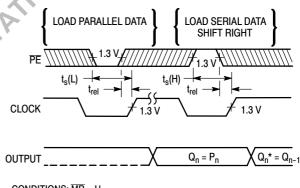


Figure 2. Master Reset Pulse Width, Master Reset to Output Delay and Master Reset to Clock Recovery Time

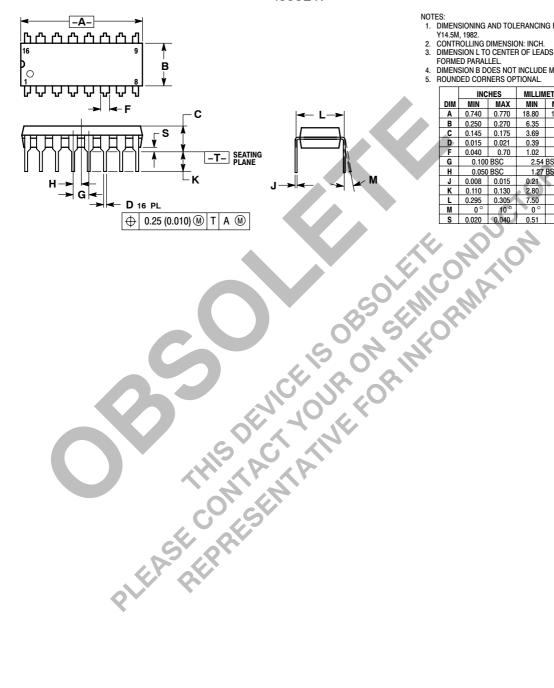


CONDITIONS: \overline{MR} = H *Q₀ STATE WILL BE DETERMINED BY J AND \overline{K} INPUTS.

Figure 4. Setup (t_s) and Hold (t_h) Time for $\overline{\text{PE}}$ Input

PACKAGE DIMENSIONS

N SUFFIX PLASTIC PACKAGE CASE 648-08 **ISSUE R**

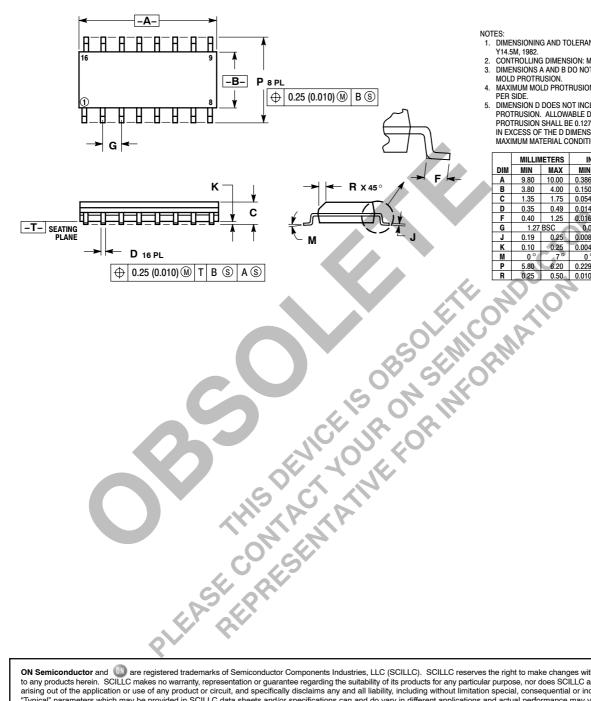


NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- CONTROLLING DIMENSION: INCH.
 DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL
- 4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
 5. ROUNDED CORNERS OPTIONAL.

		INC	HES	MILLIN	IETERS		
	DIM	MIN	MAX	MIN	MAX		
	Α	0.740	0.770	18.80	19.55		
	В	0.250	0.270	6.35	6.85		
	Ç	0.145	0.175	3.69	4.44		
4	Ď	0.015	0.021	0.39	0.53		
	F	0.040	0.70	1.02	1.77		
	G	0.100	BSC	2.54	BSC		
	Н	0.050	BSC	1.27 BSC			
	J	0.008	0.015	0.21	0.38		
	K	0.110	0.130	2.80	3.30		
	L	0.295	0.305	7.50	7.74		
	M	0°	10°	0 °	10 °		
	9	0.020	0.040	0.51	1.01		

D SUFFIX PLASTIC SOIC PACKAGE CASE 751B-05 **ISSUE J**



NOTES:

- 1. DIMENSIONING AND TOLERANCING PER ANSI
- Y14.5M, 1982. CONTROLLING DIMENSION: MILLIMETER.
- DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
- MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE
- DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE DIDIMENSION AT MAXIMUM MATERIAL CONDITION.

	MILLIN	IETERS	INCHES		
DIM	MIN	MAX	MIN	MAX	
Α	9.80	10.00	0.386	0.393	
В	3.80 4.00		0.150	0.157	
С	1.35	1.75	0.054	0.068	
D	0.35	0.49	0.014	0.019	
F	0.40	1.25	0.016	0.049	
G	1.27	BSC	0.050 BSC		
J	0.19	0.19 0.25		0.009	
K	0.10	0.25	0.004	0.009	
M	0°	7°	0°	7°	
P	5.80	6.20	0.229	0.244	
R	0.25	0.50	0.010	0.019	

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